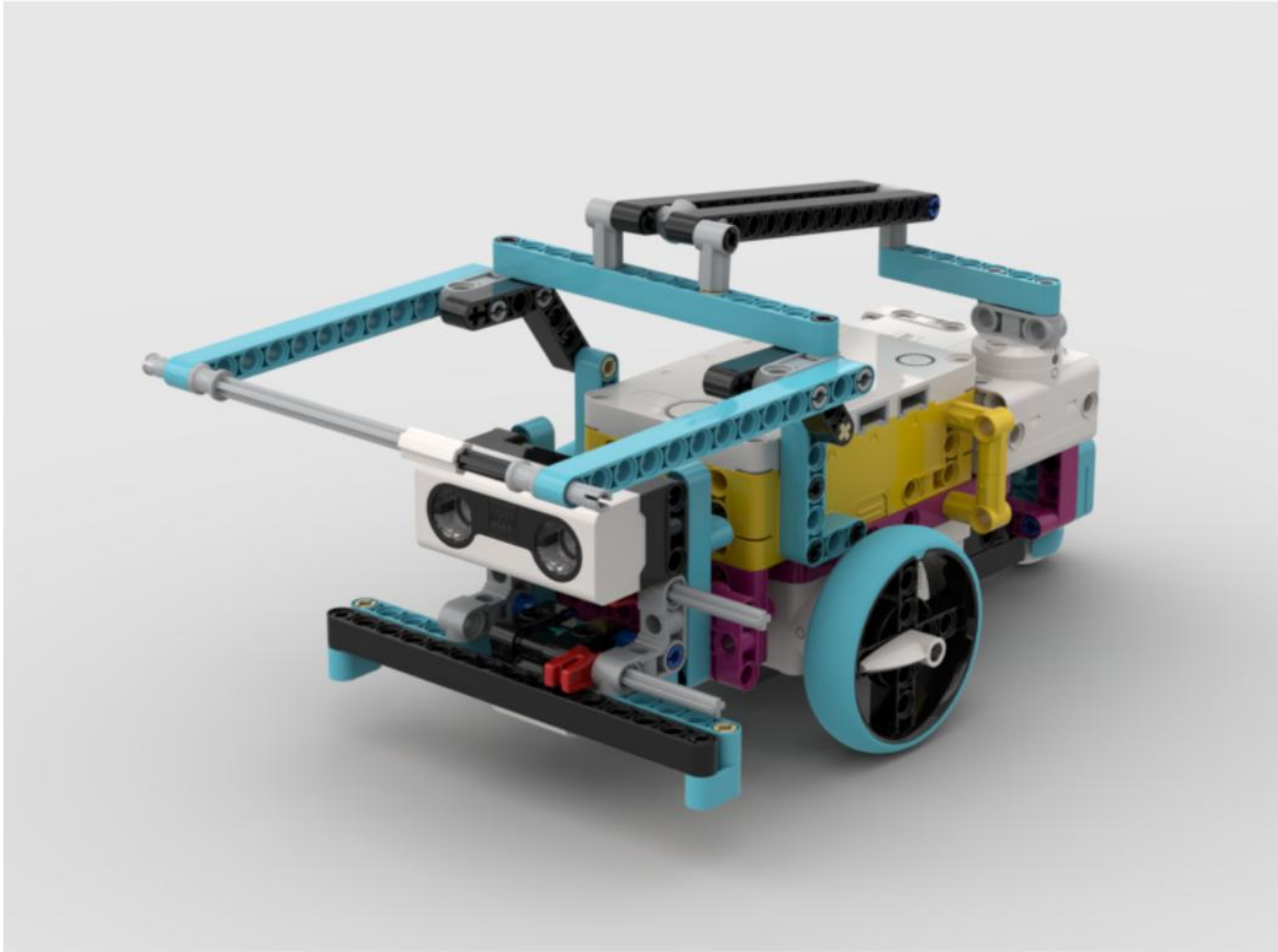
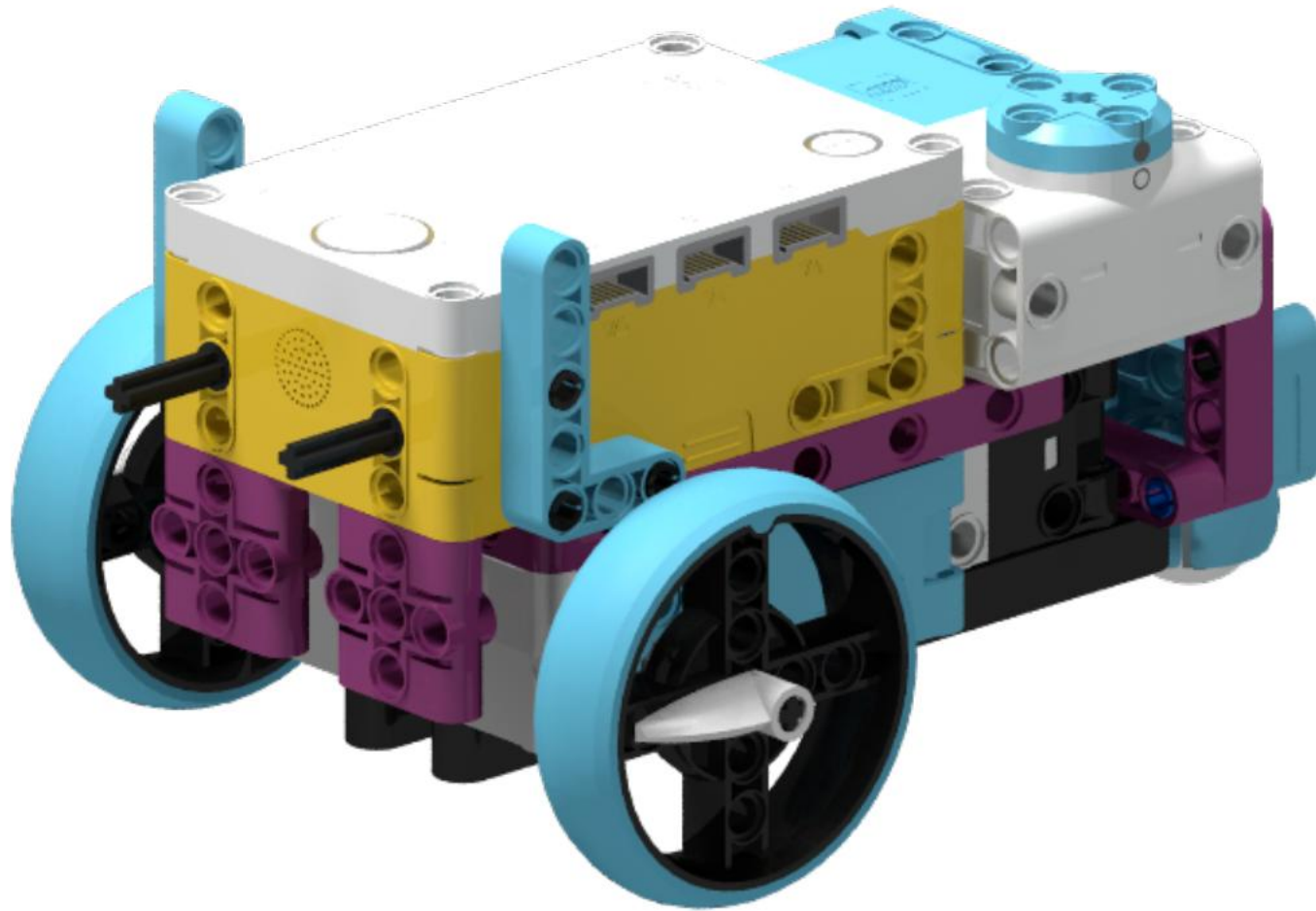


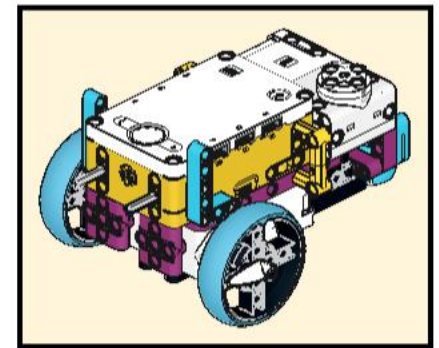
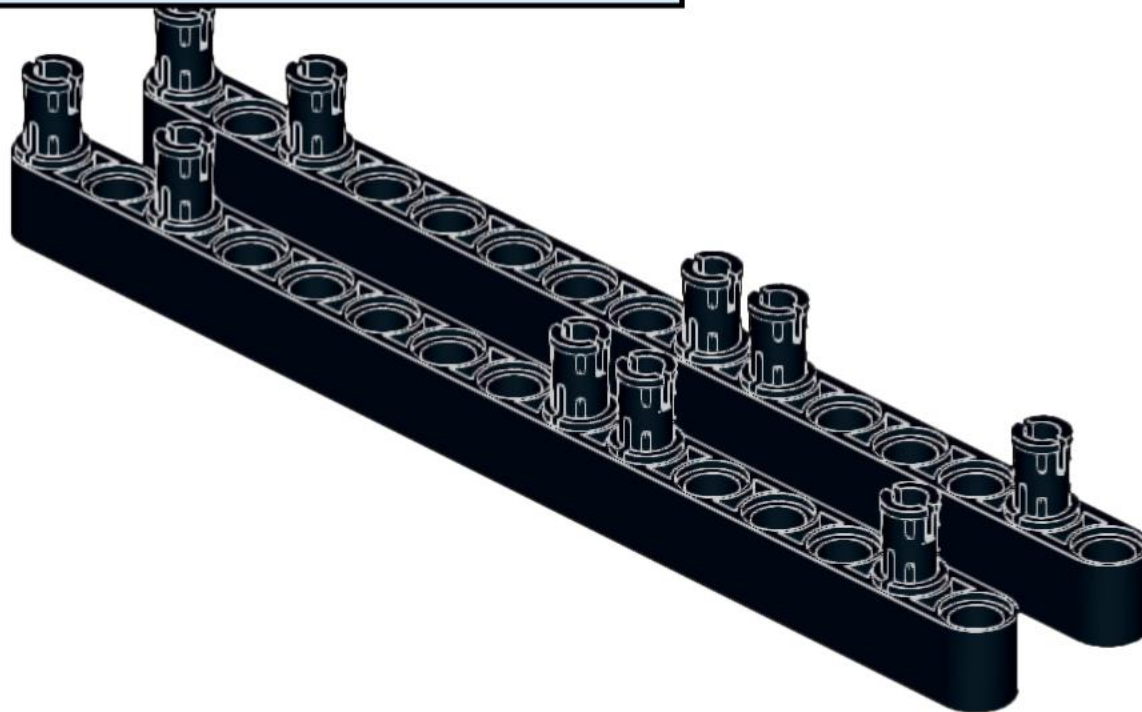
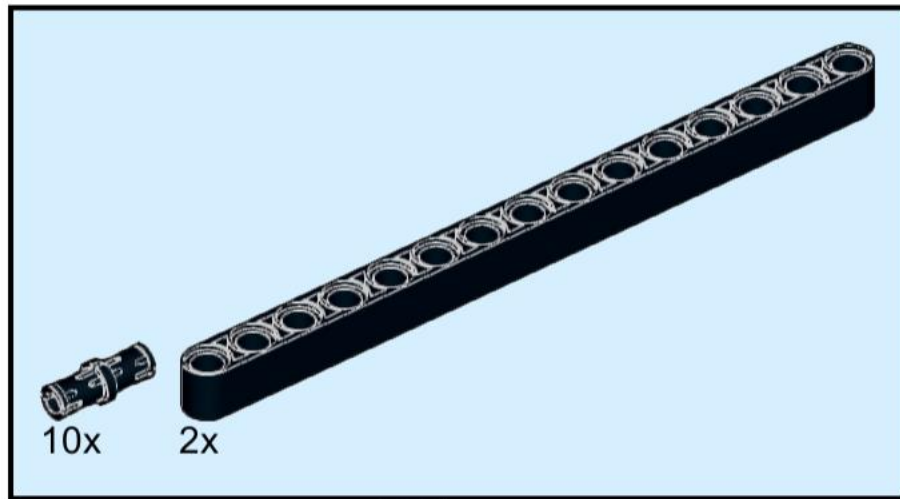
# TACObot



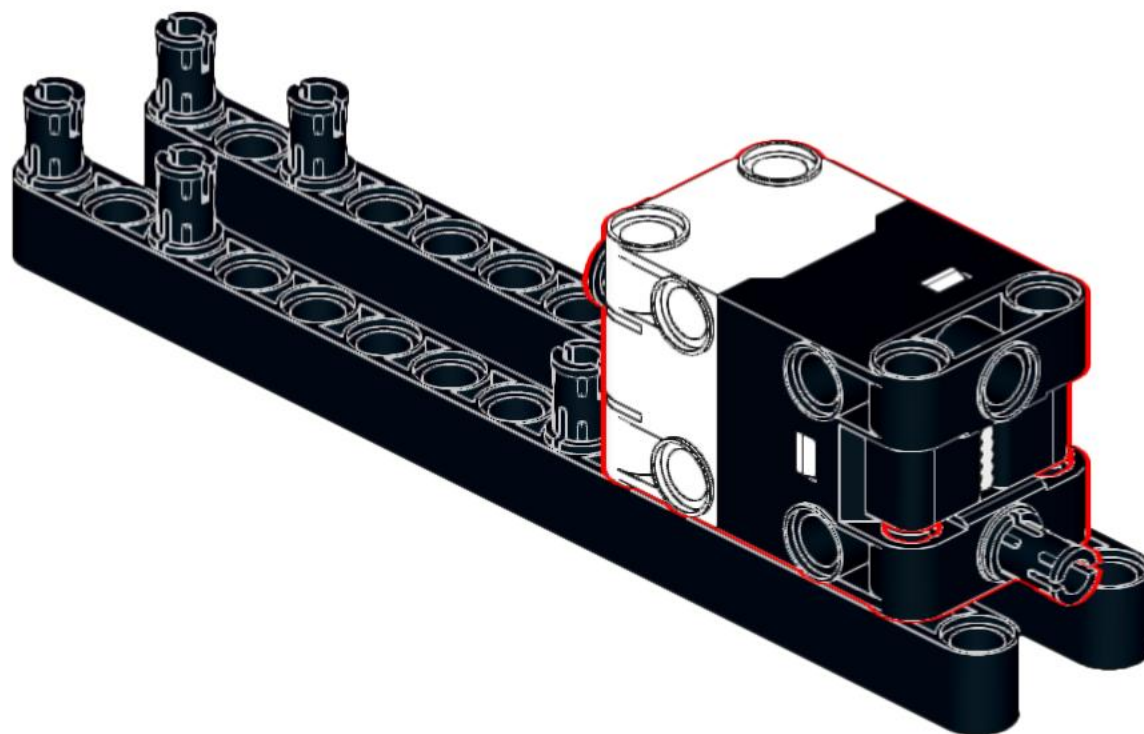
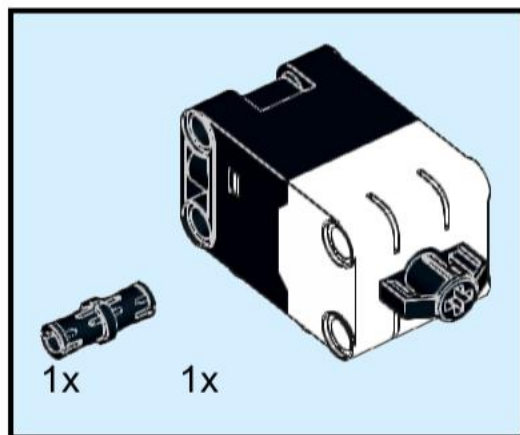
# Body



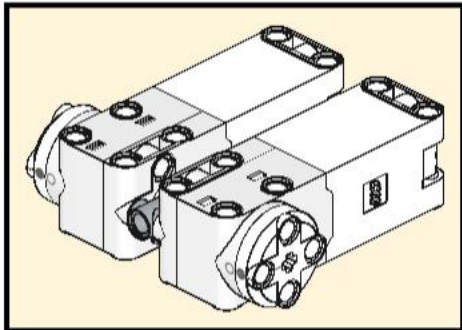
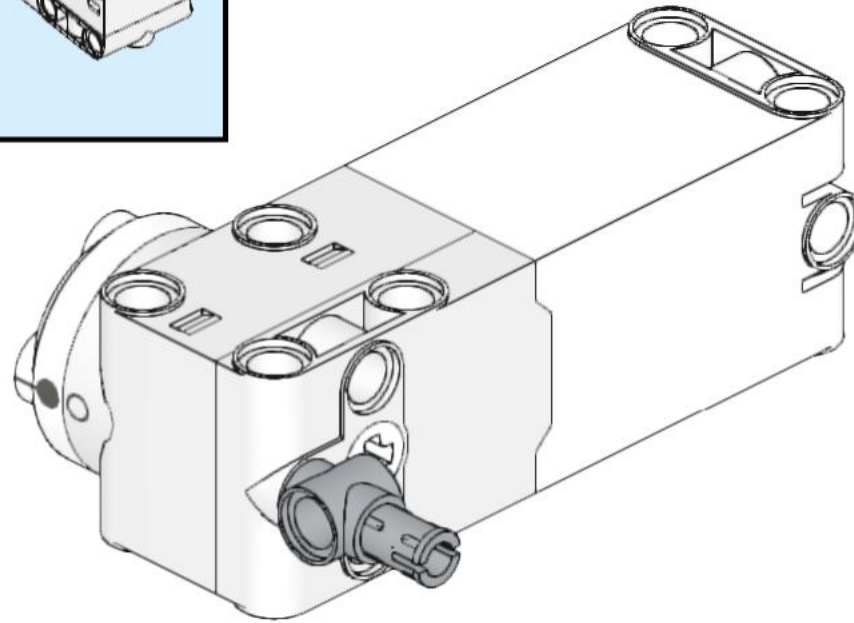
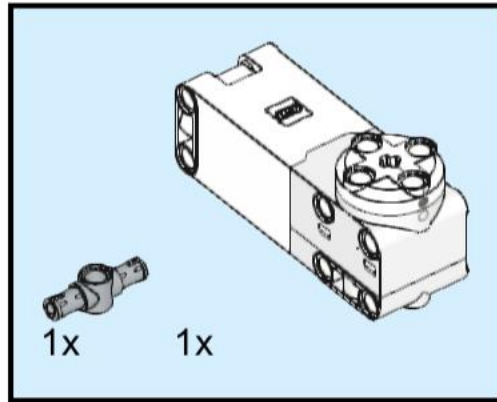
1



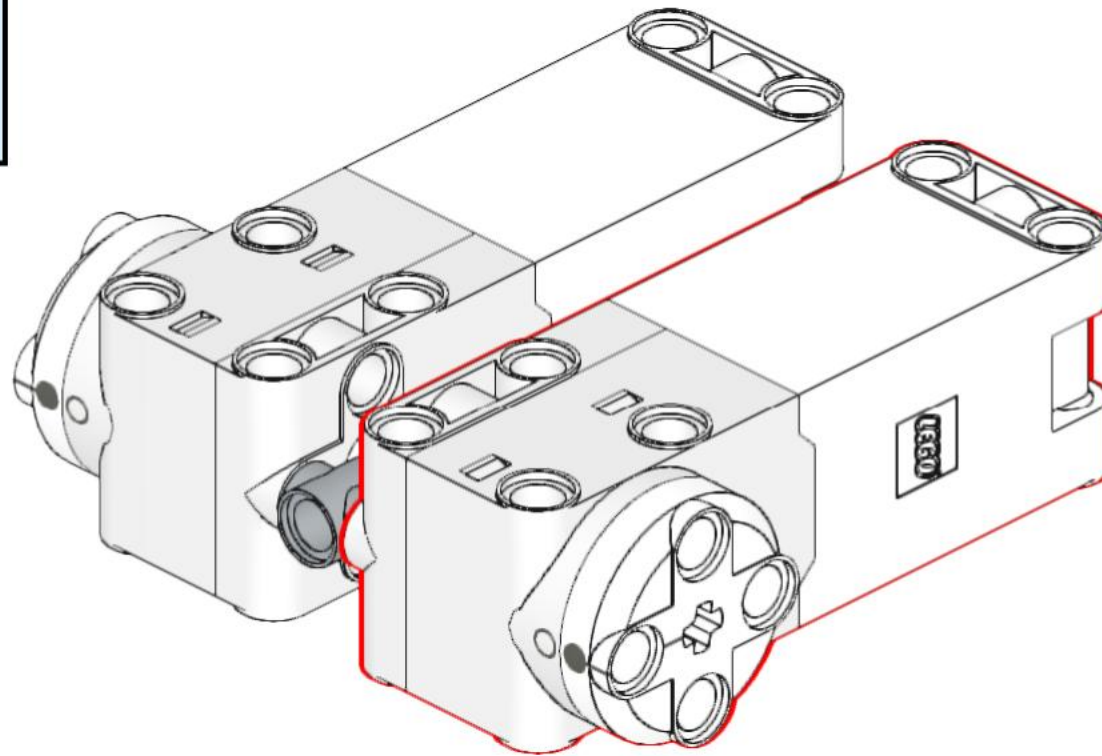
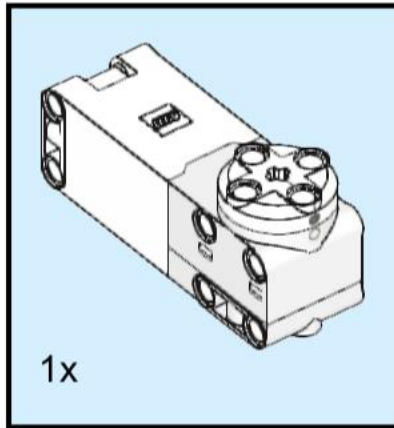
# 2



3

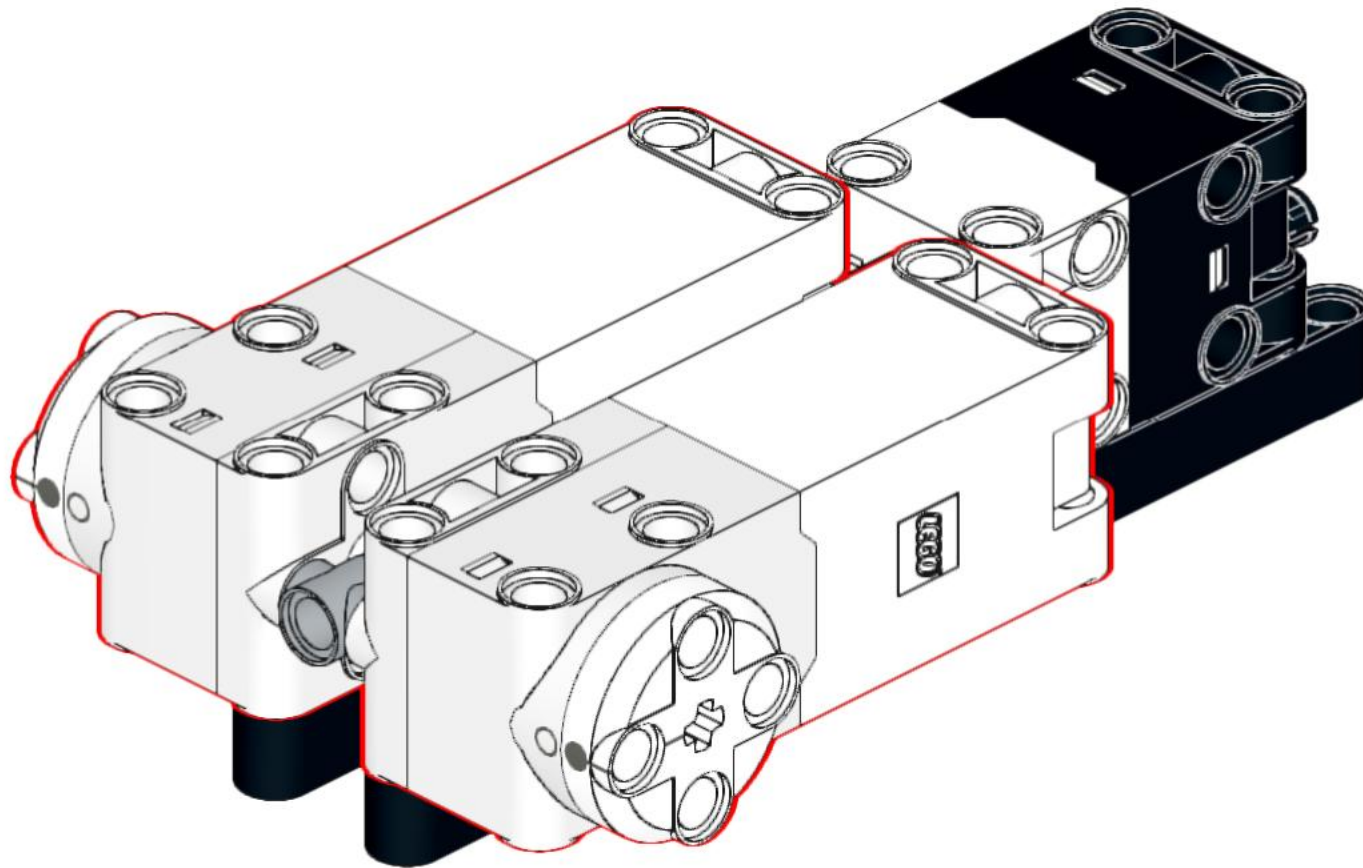


4

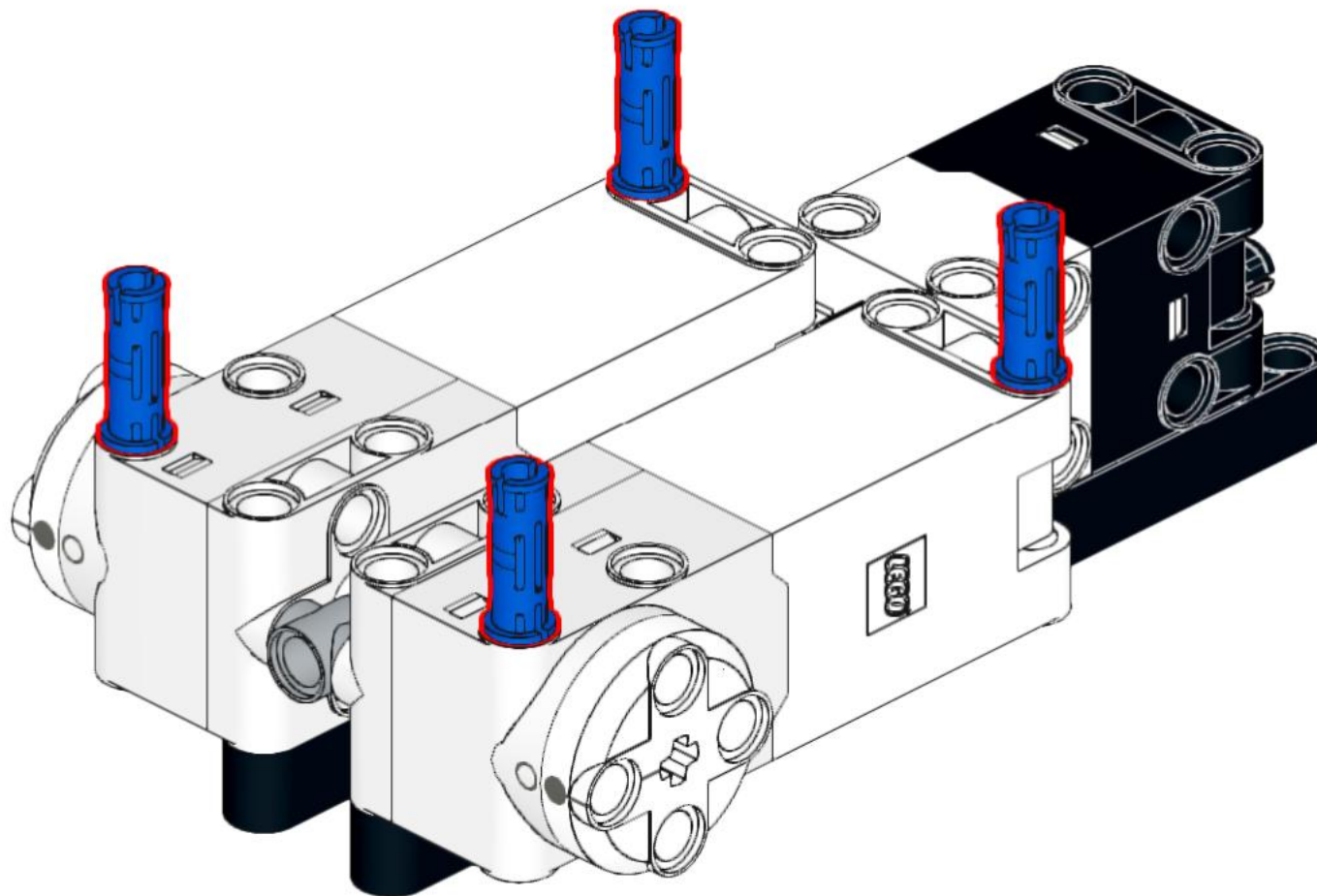
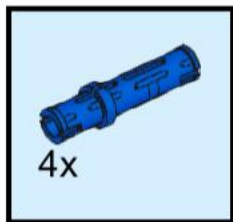




5

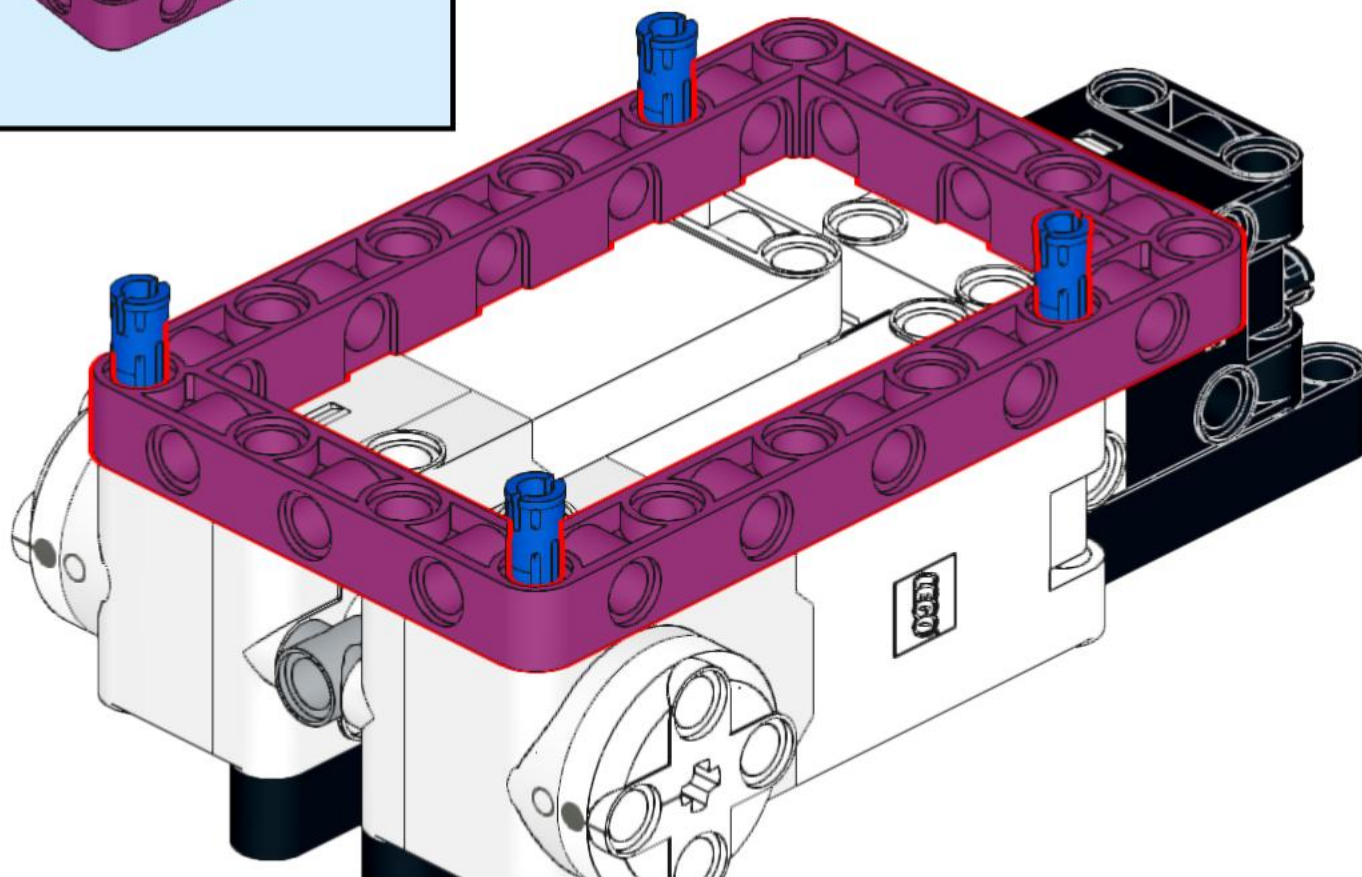
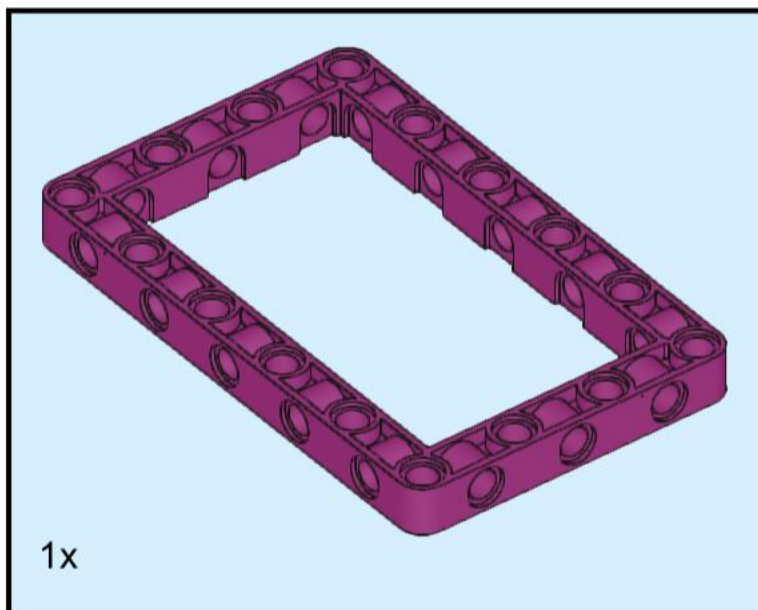


6

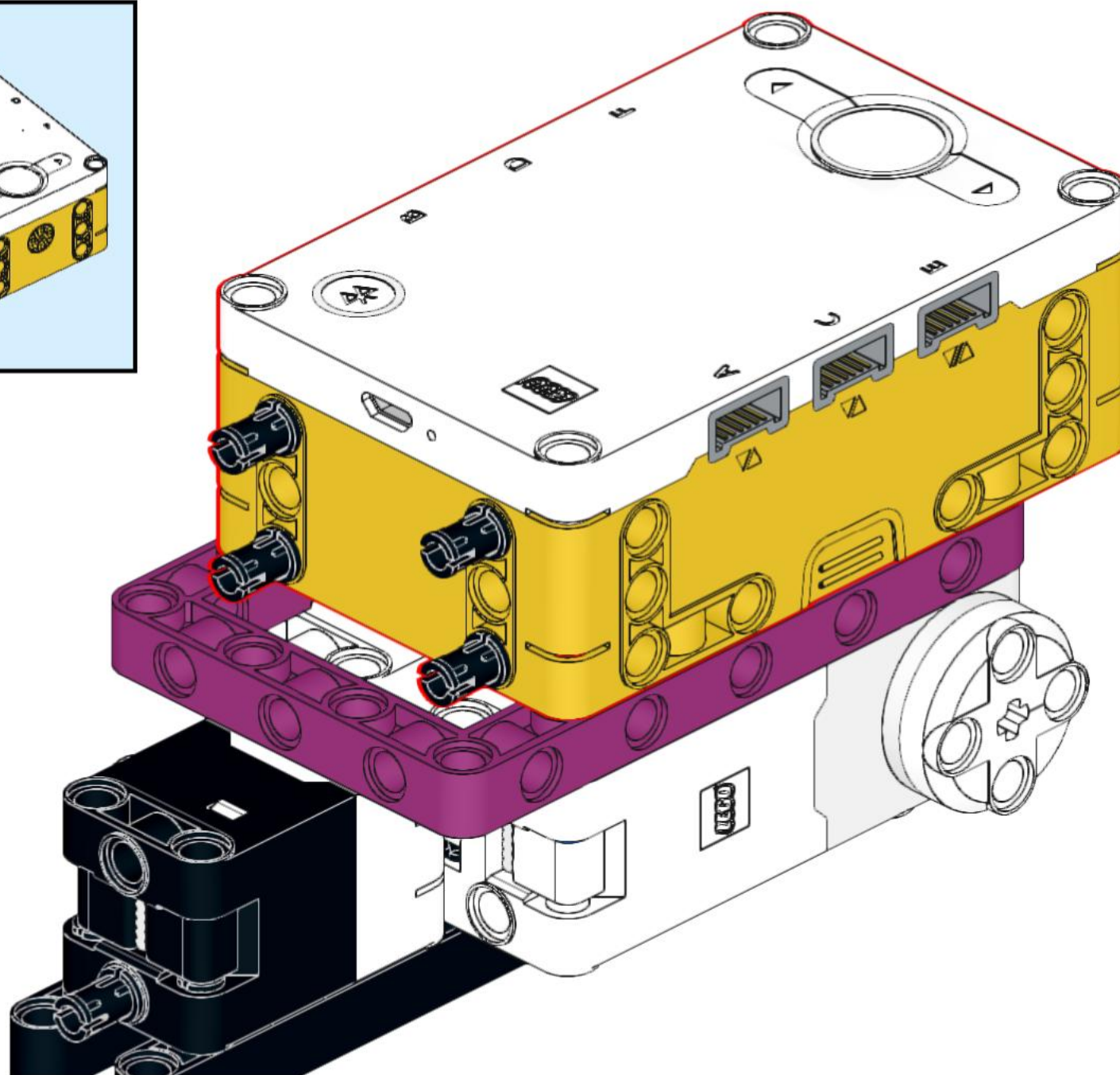
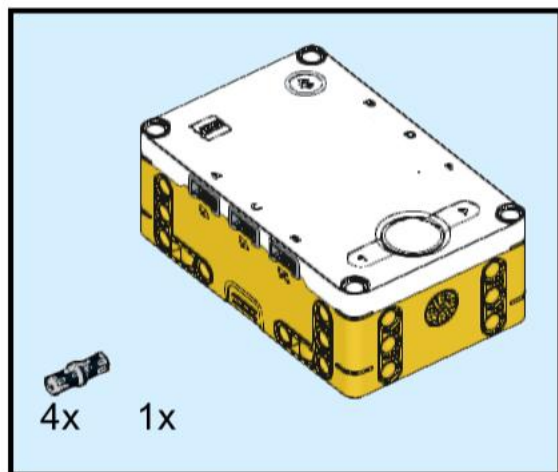




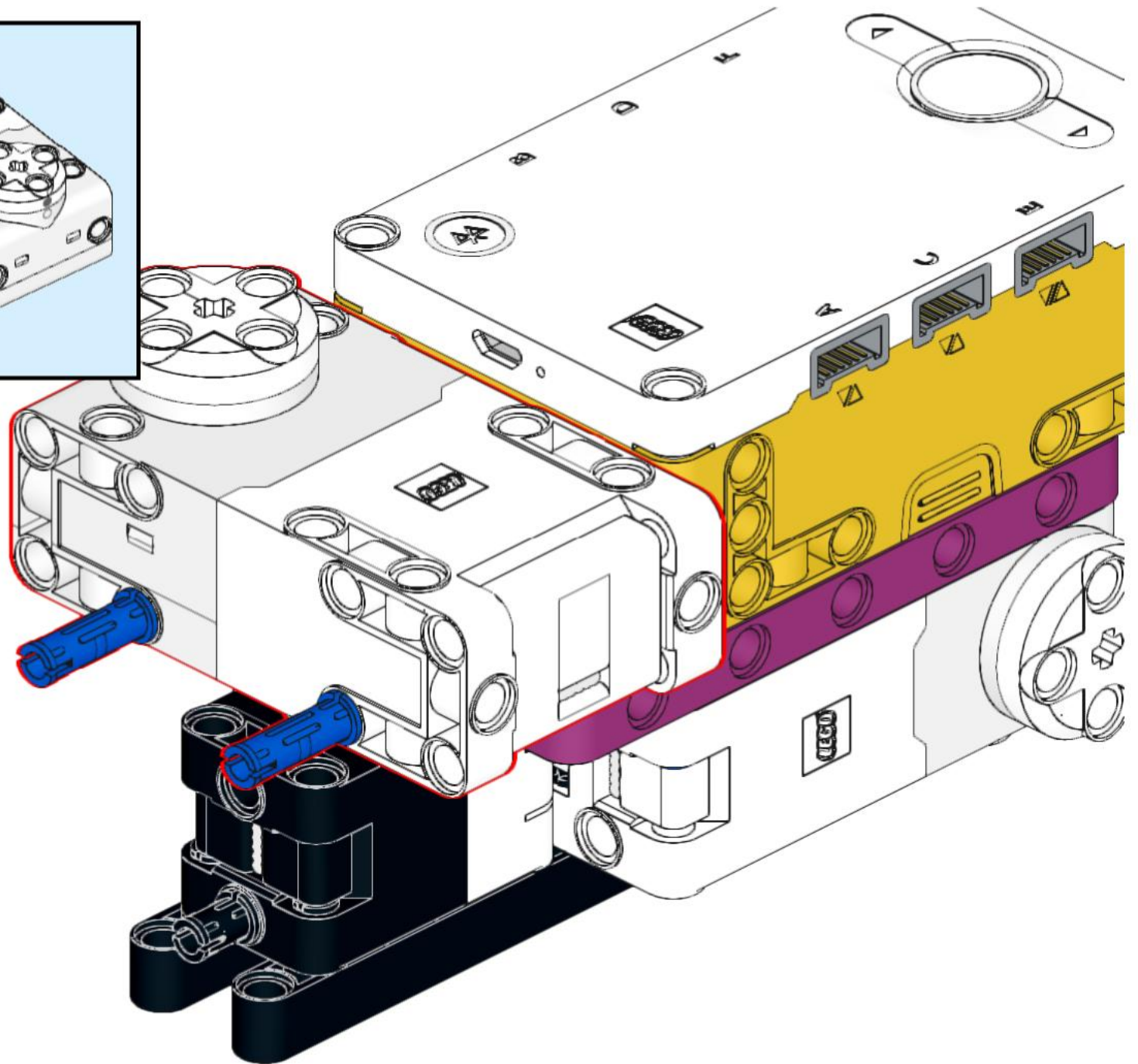
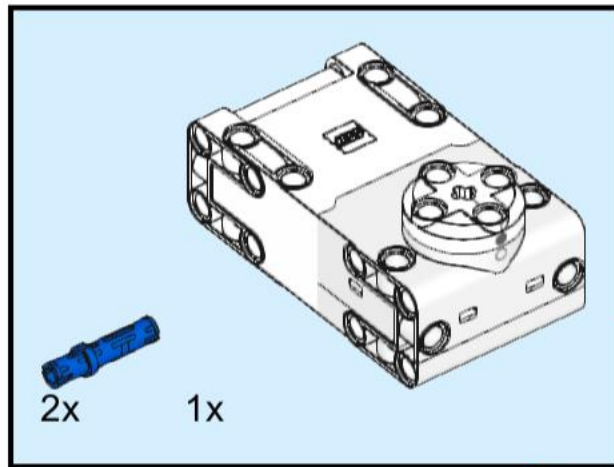
7



8

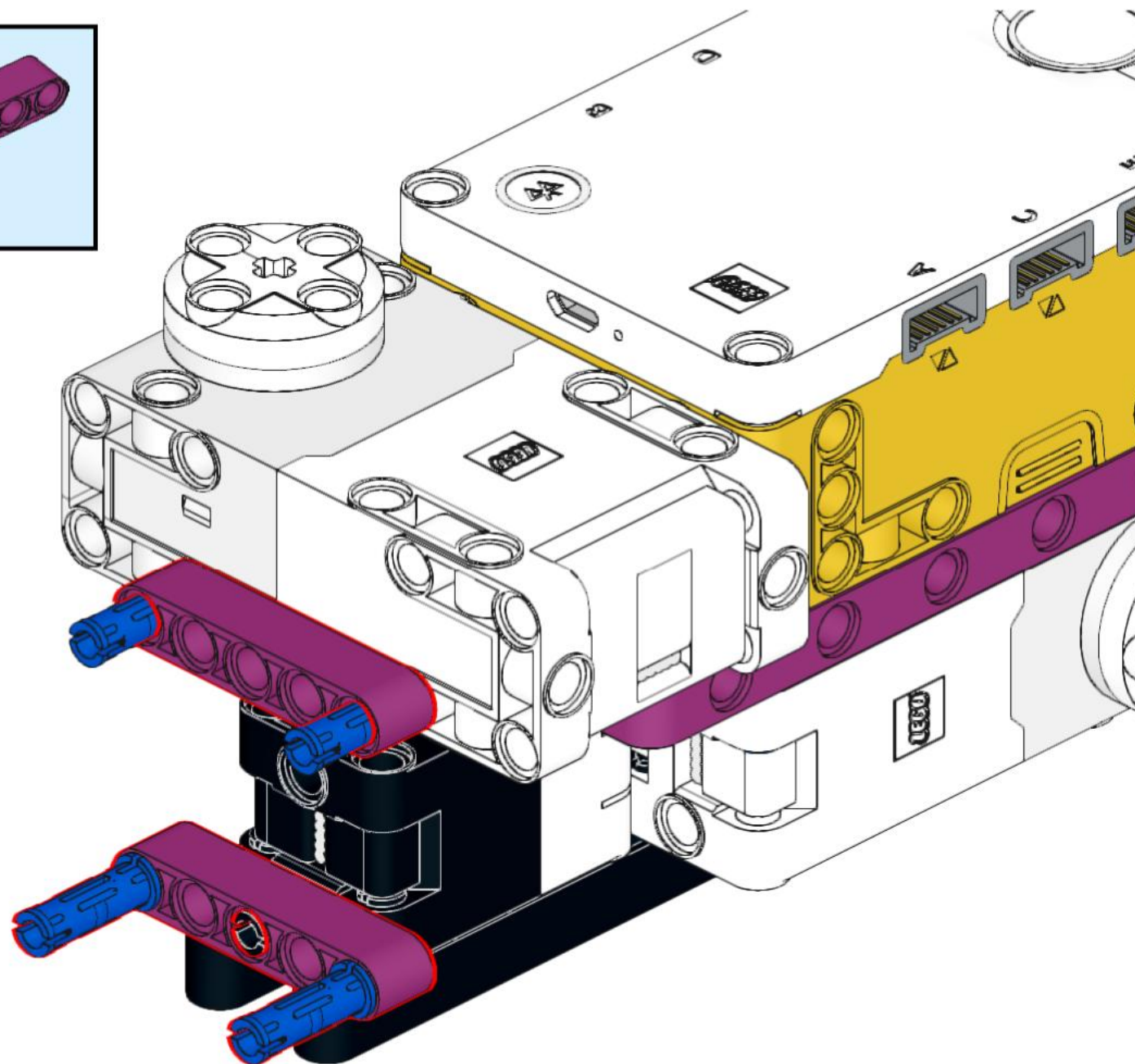
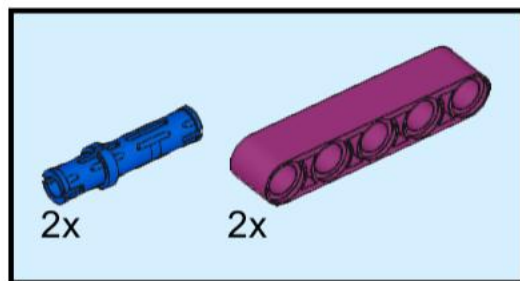


9

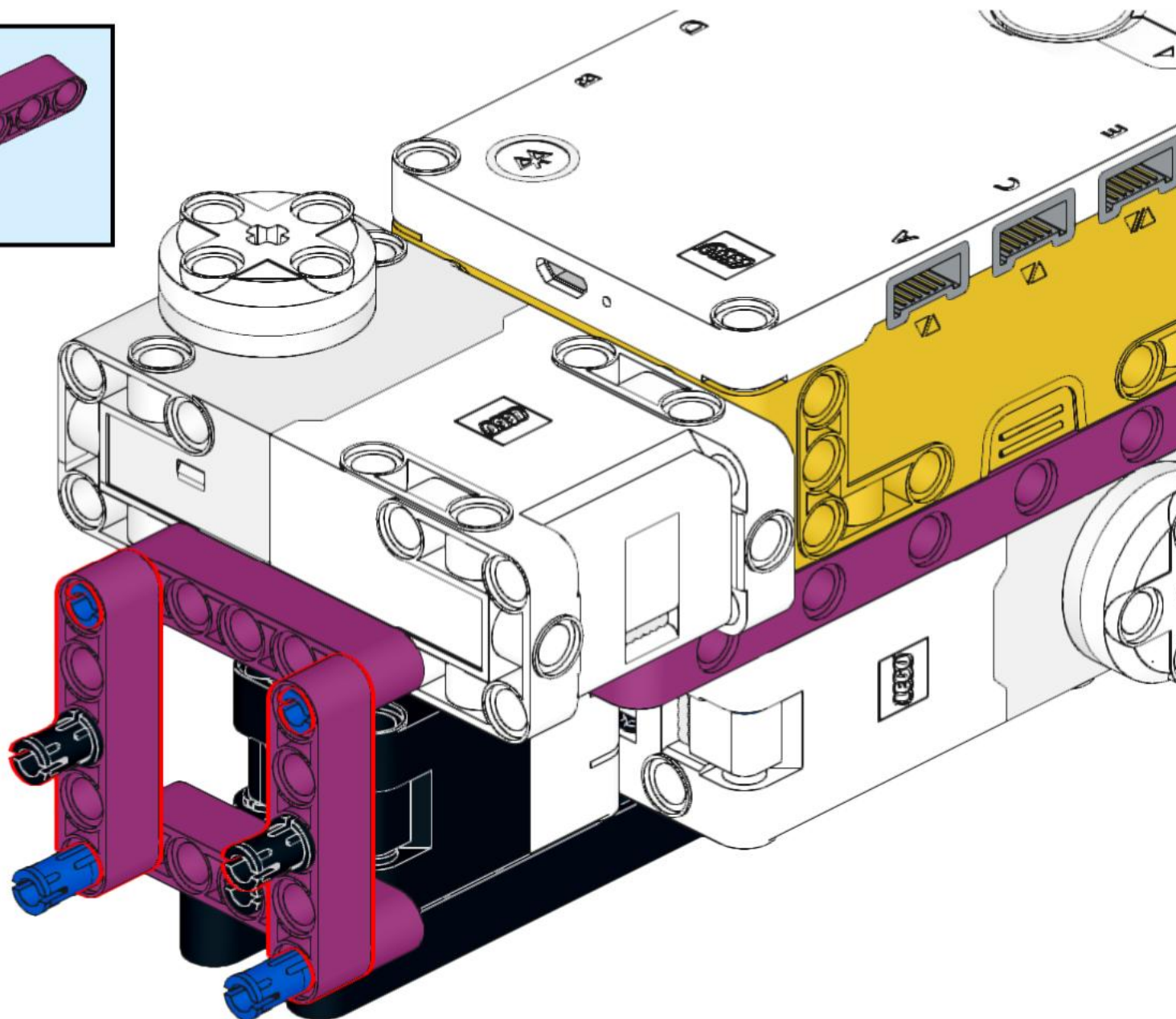
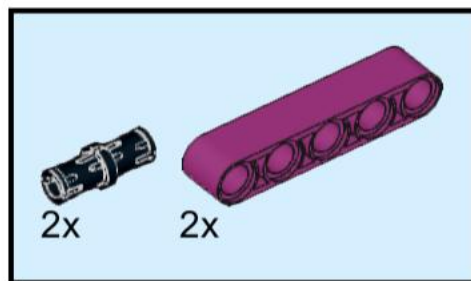




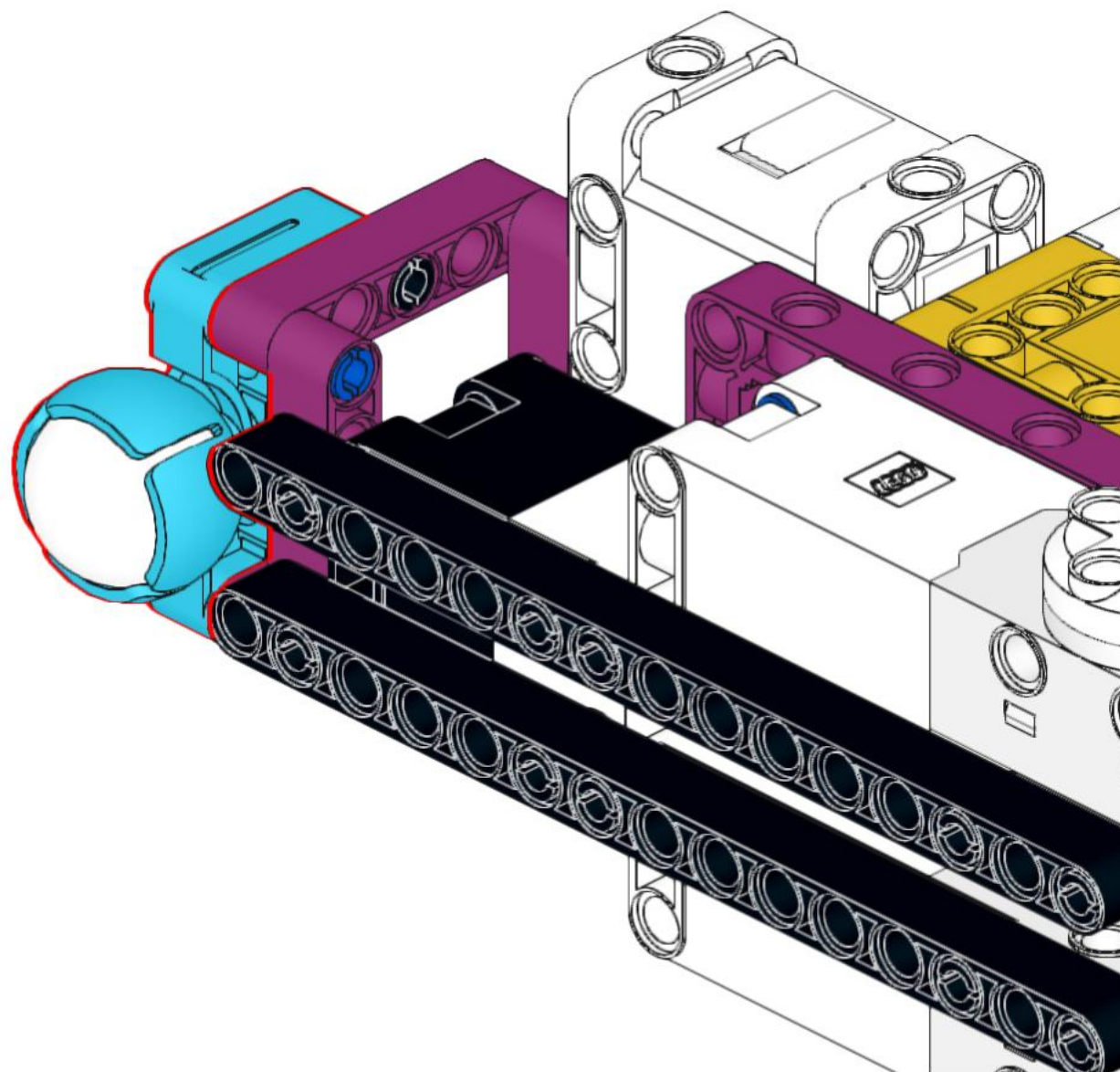
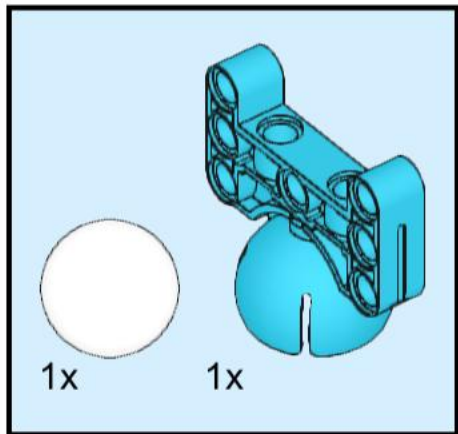
# 10



# 11

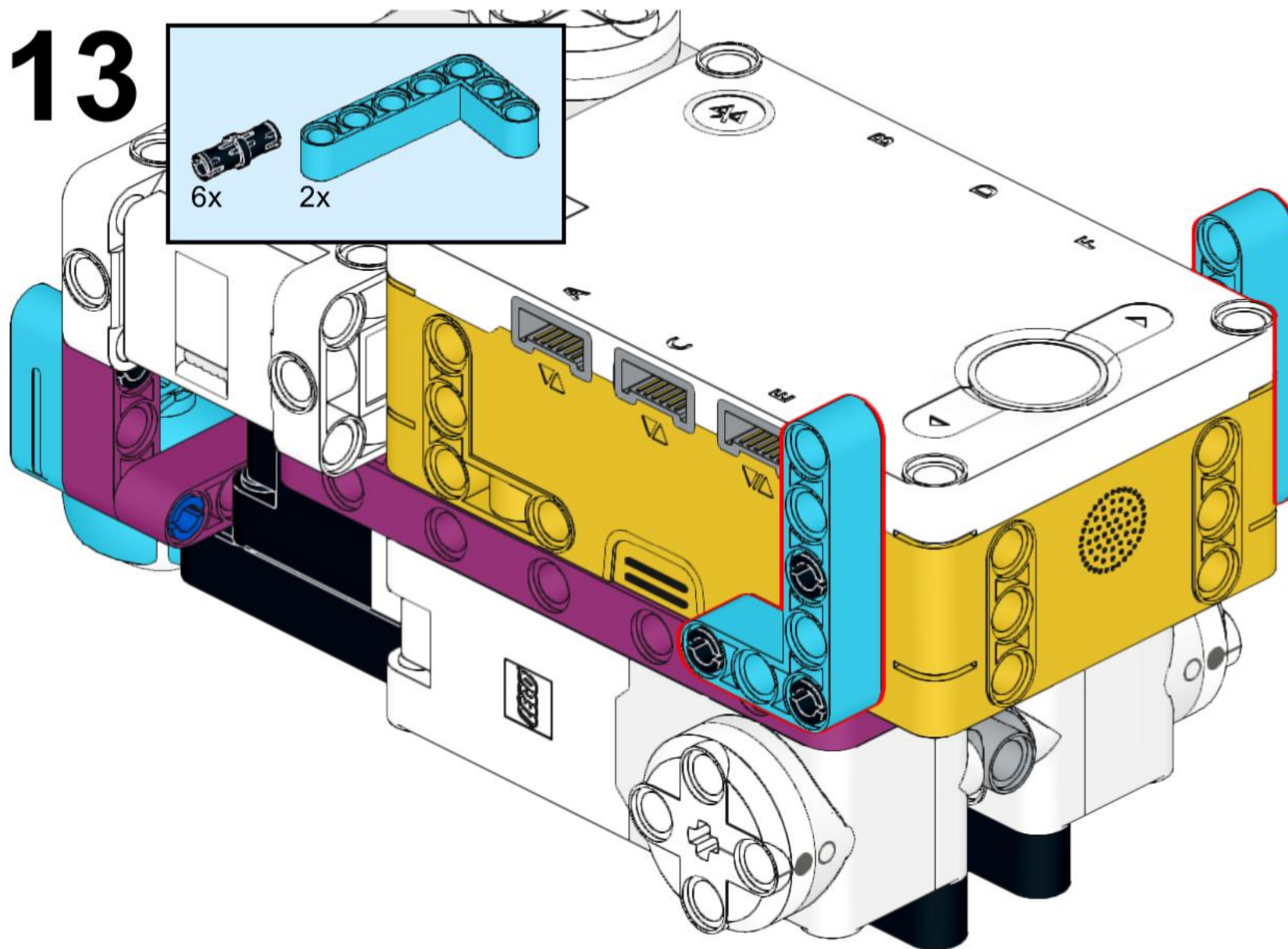


# 12

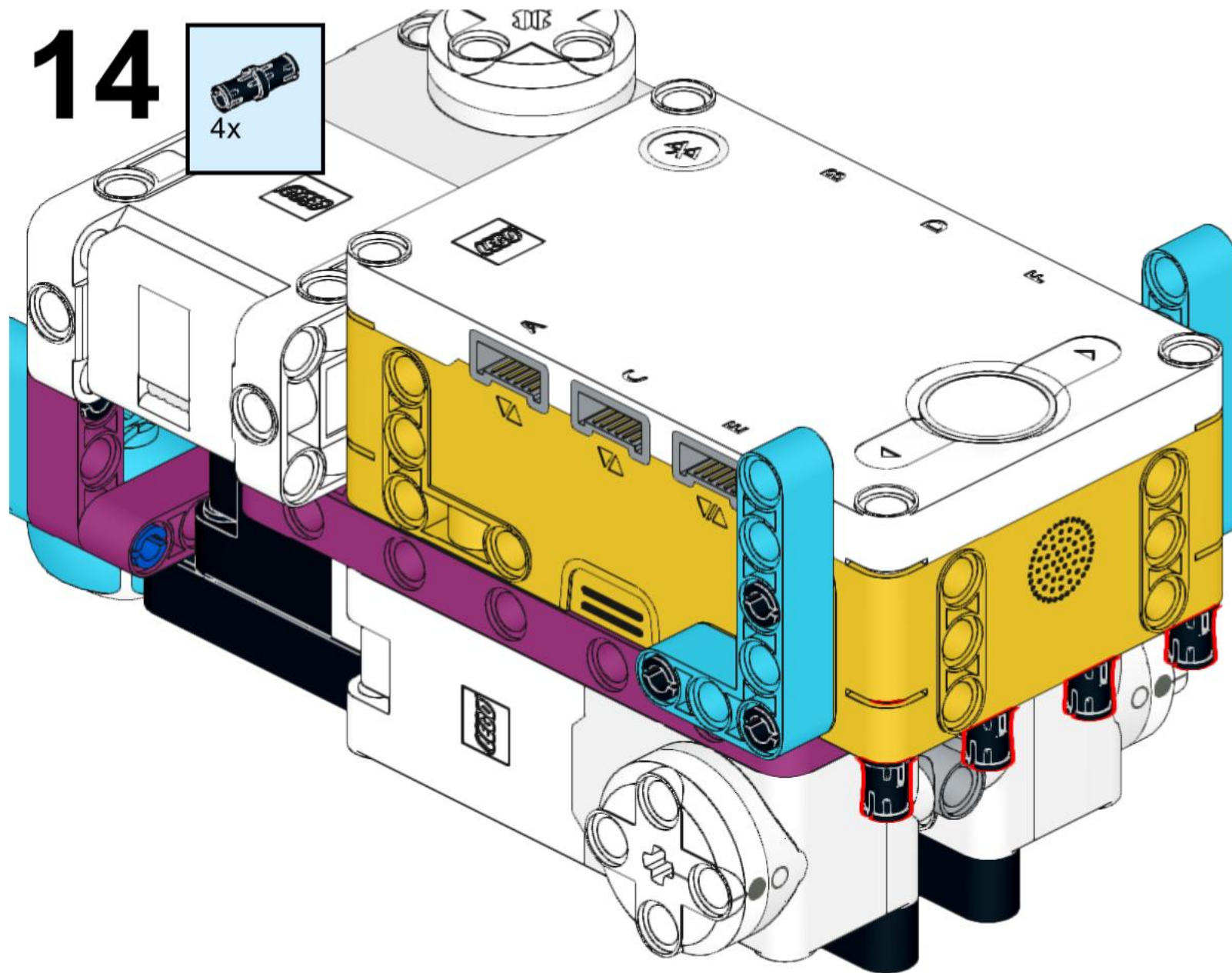




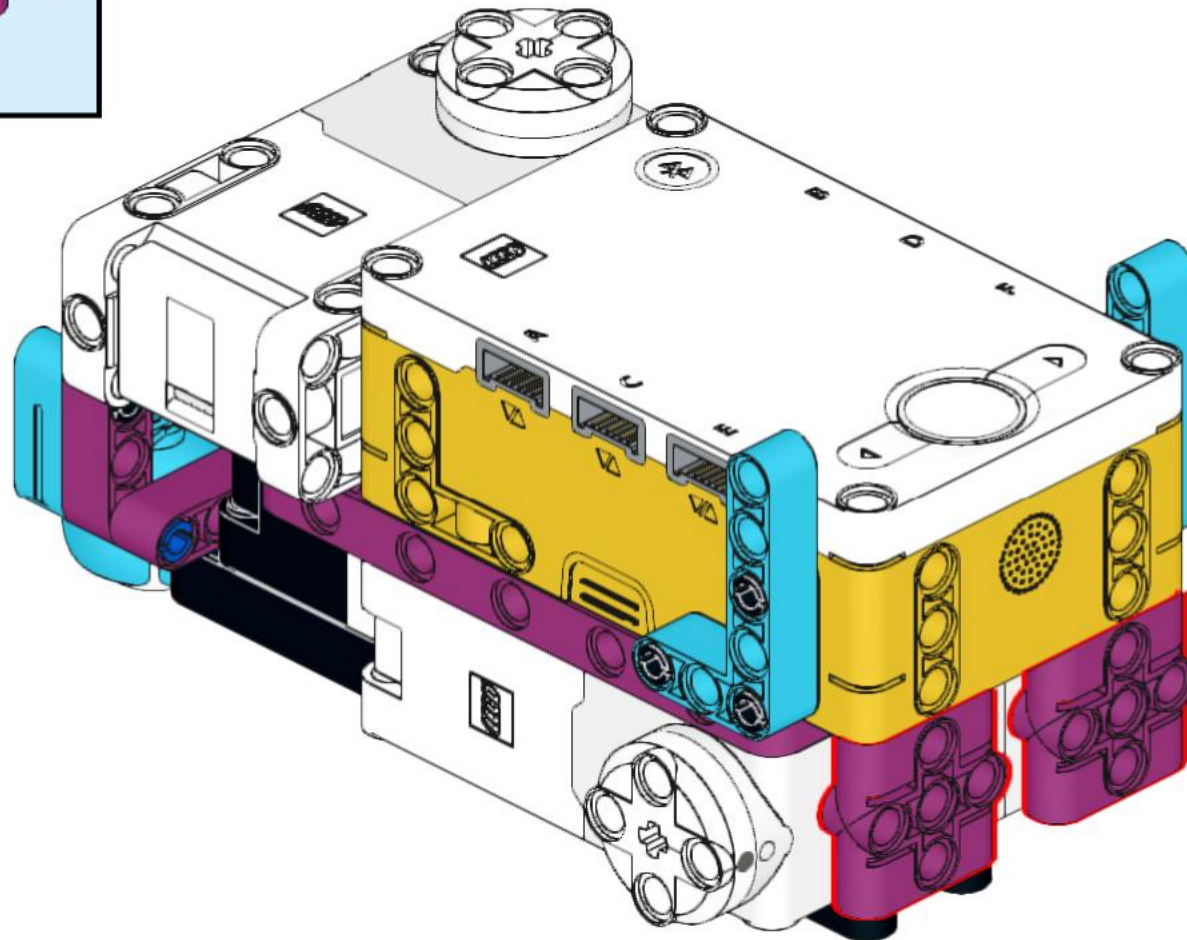
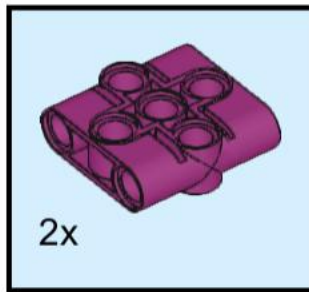
# 13



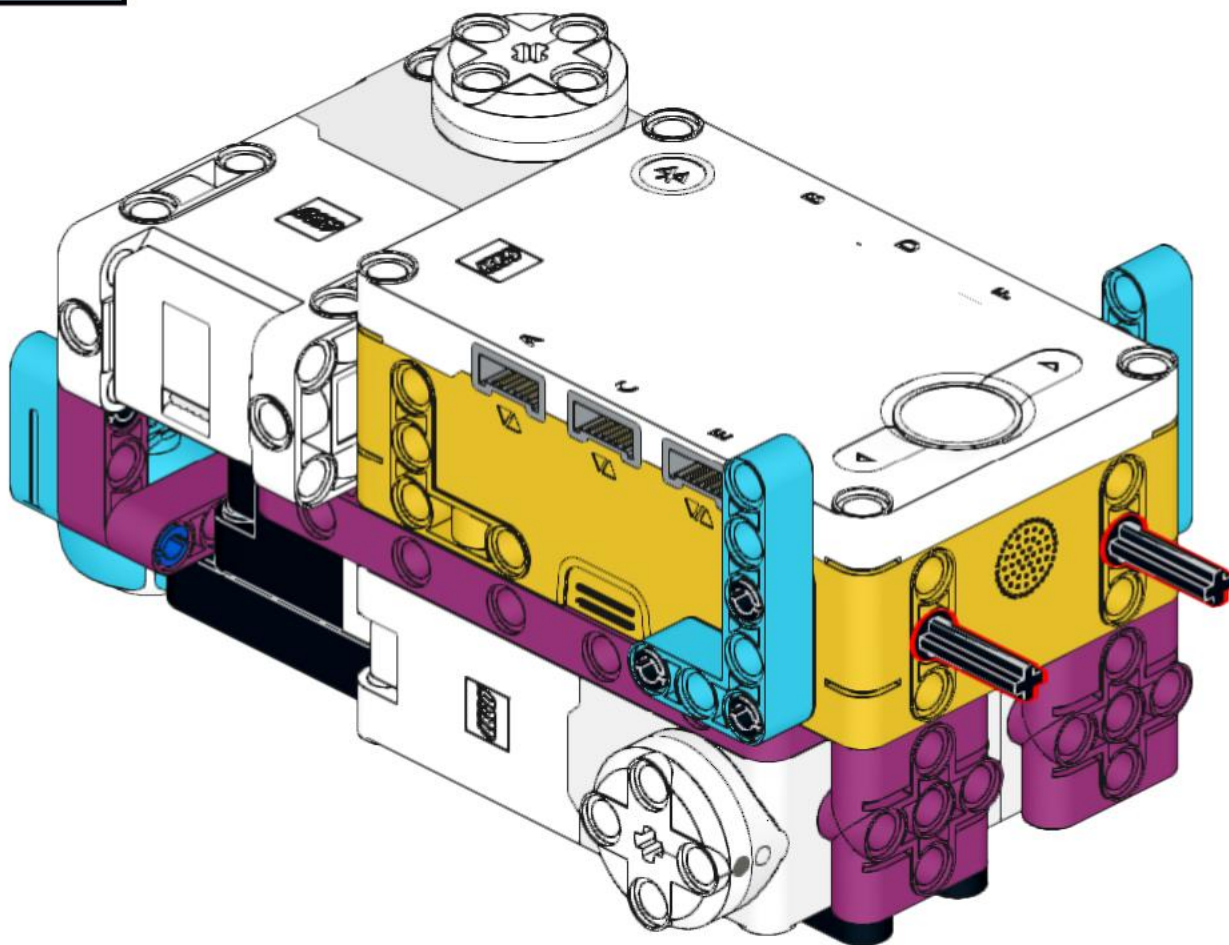
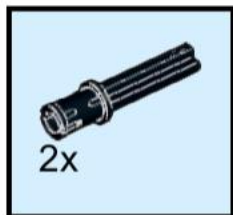
14



# 15

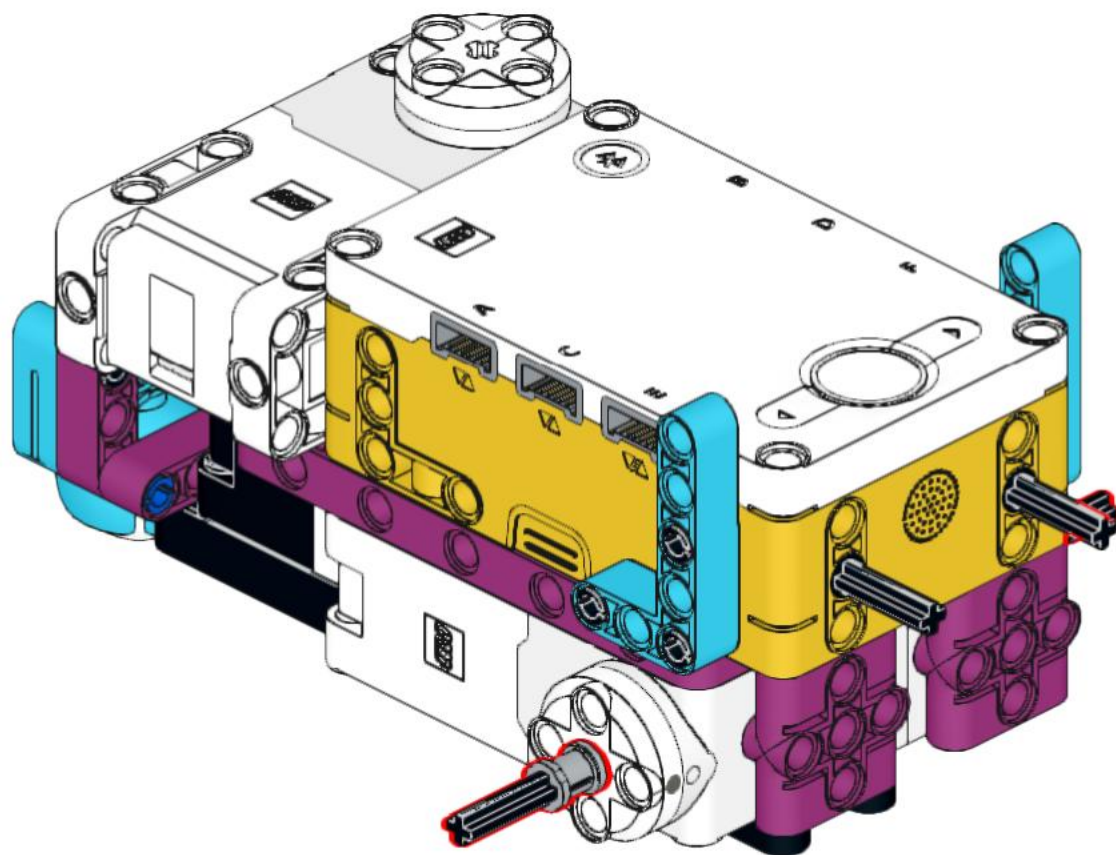
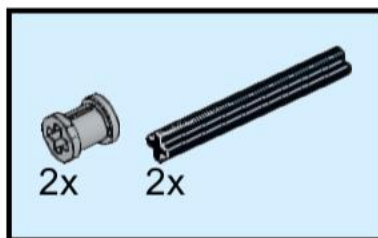


# 16

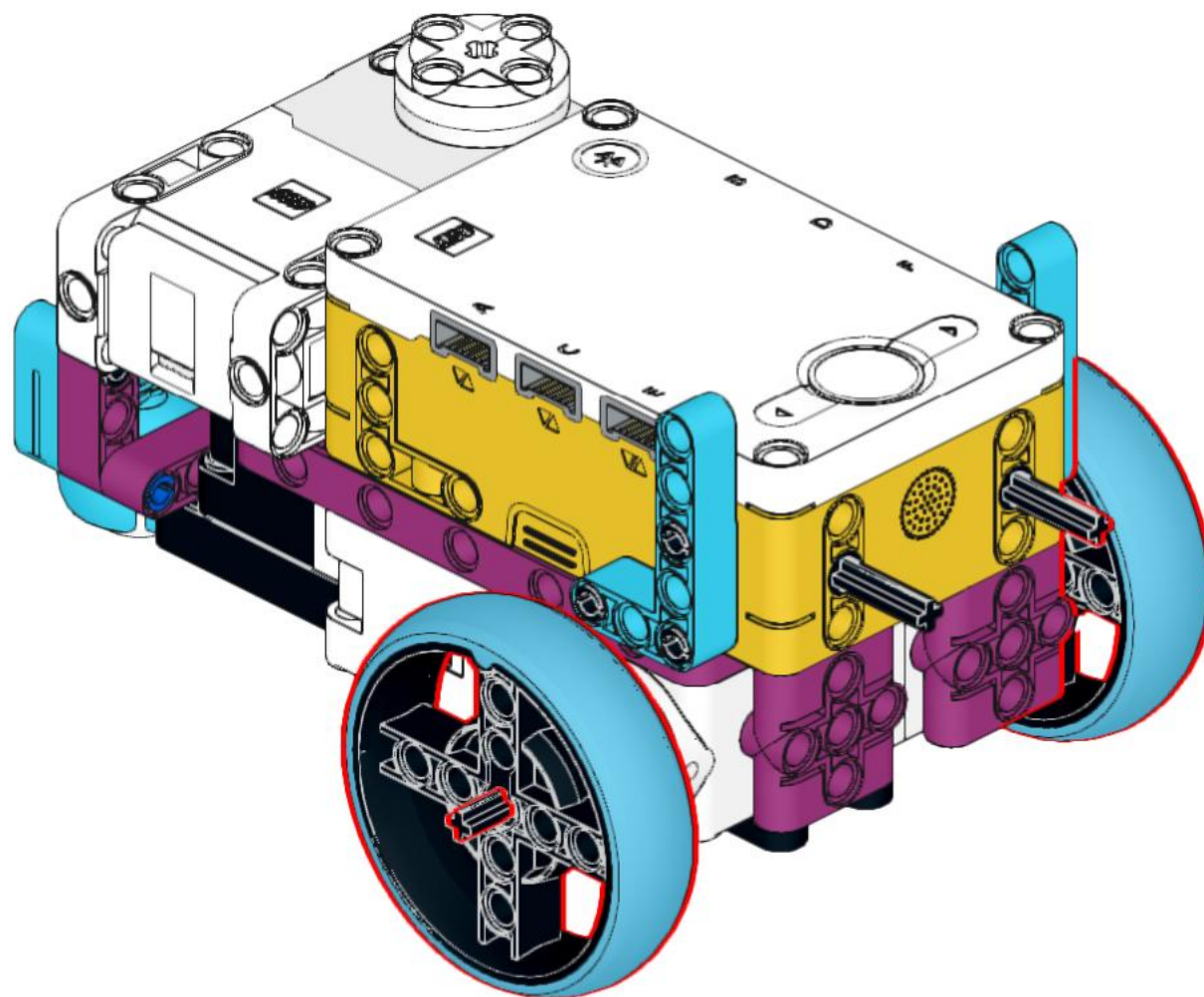
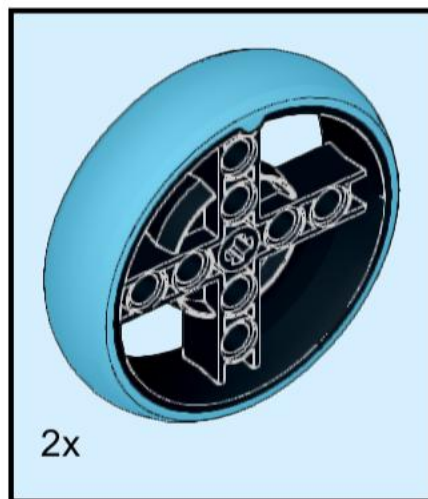




# 17

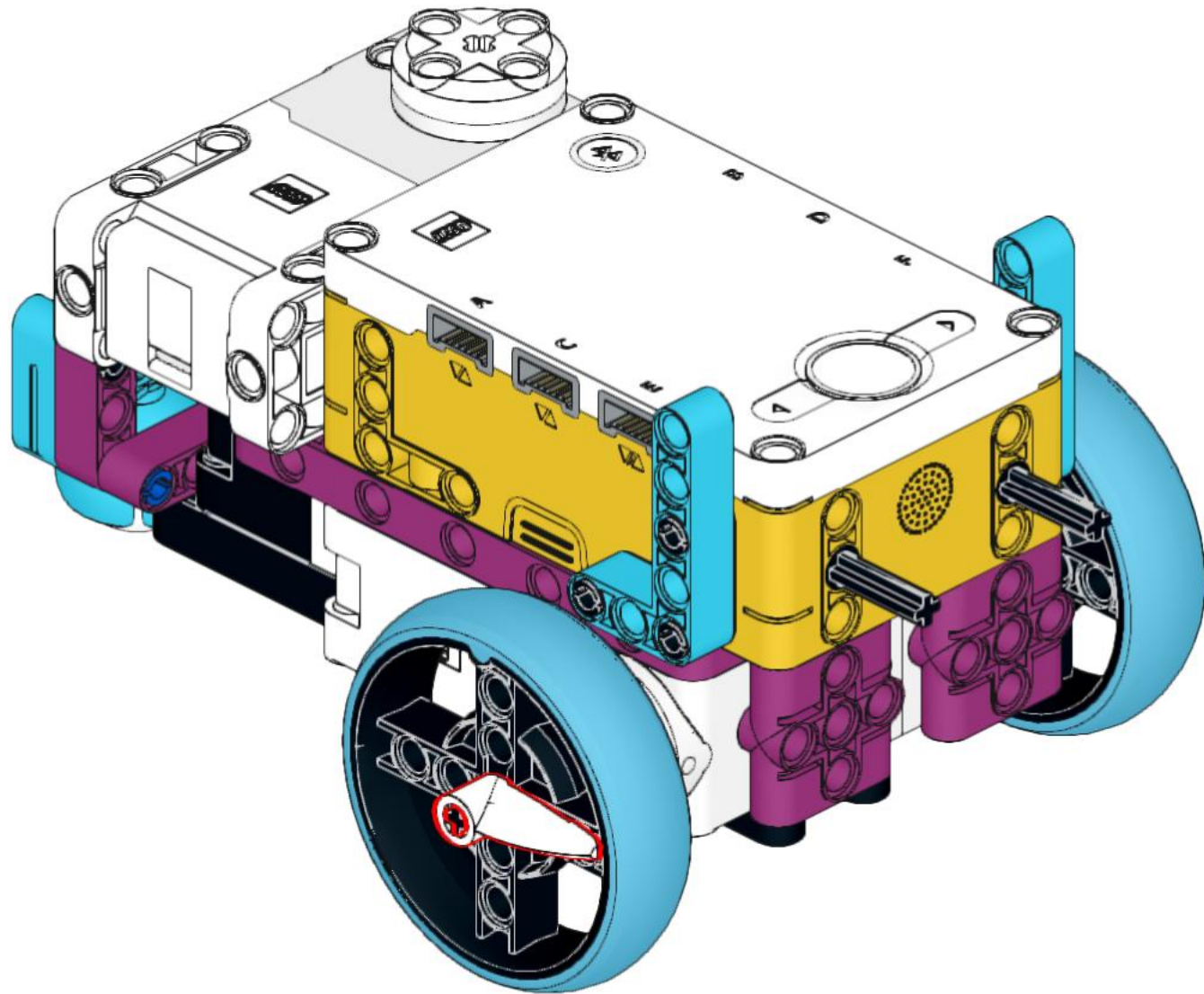
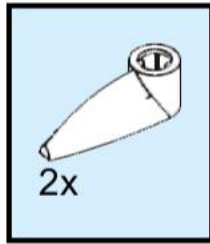


# 18

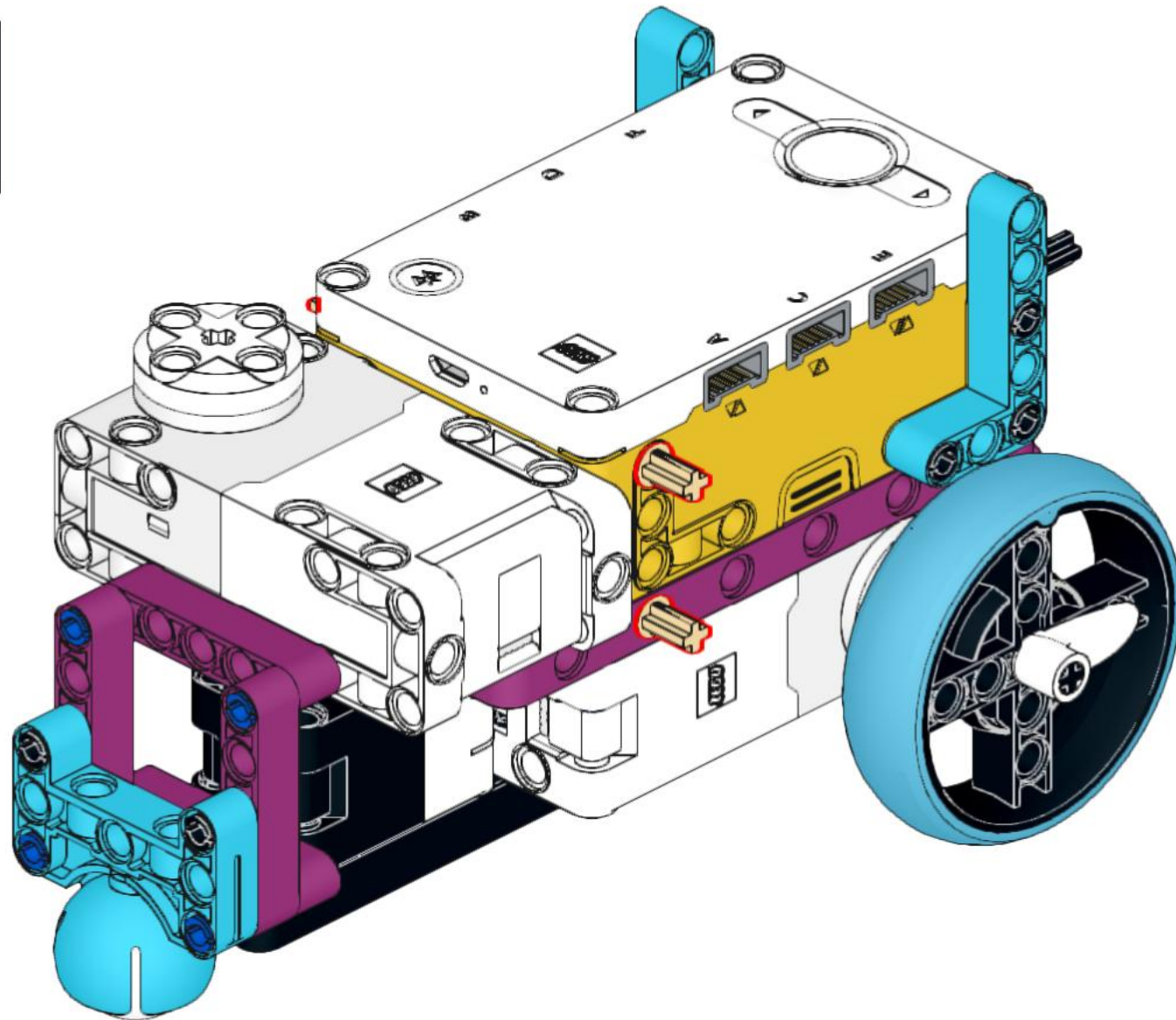
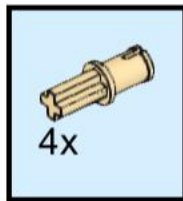




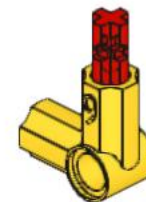
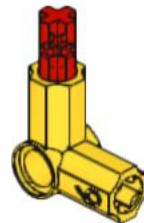
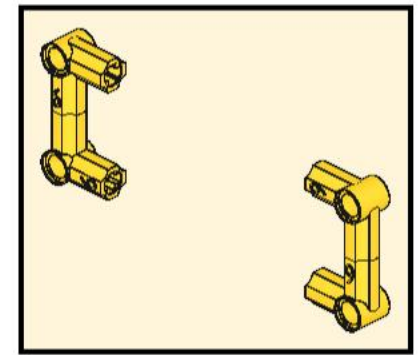
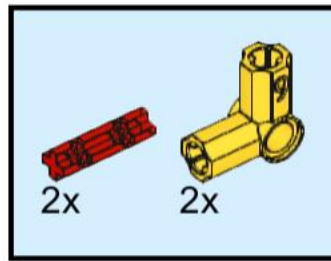
# 19



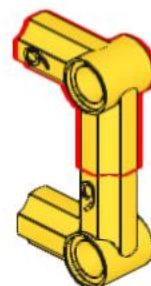
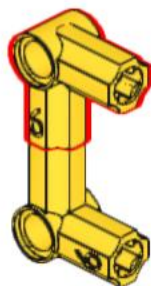
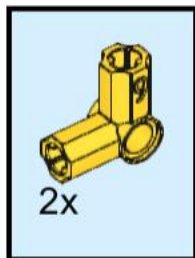
# 20



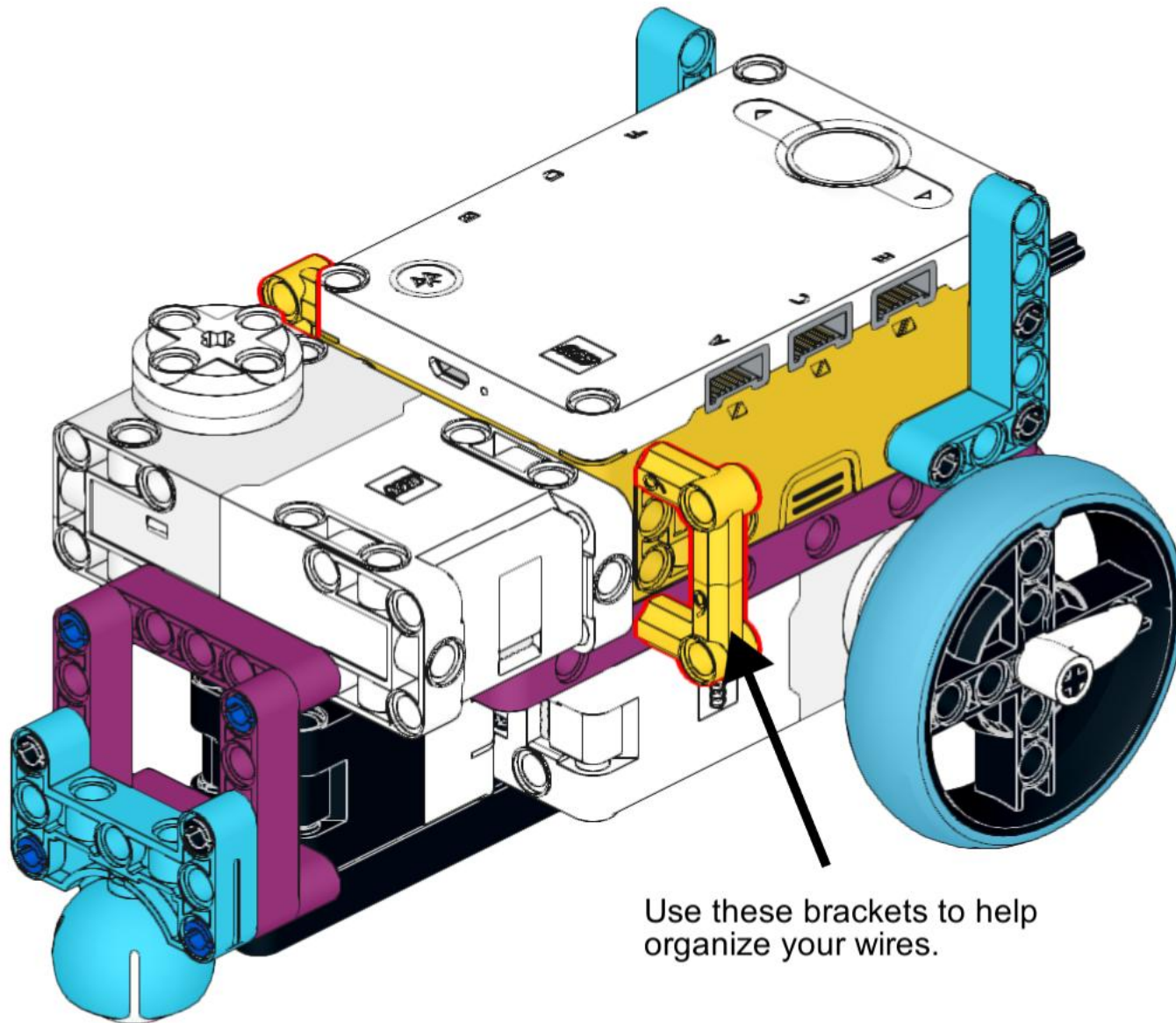
# 21



# 22



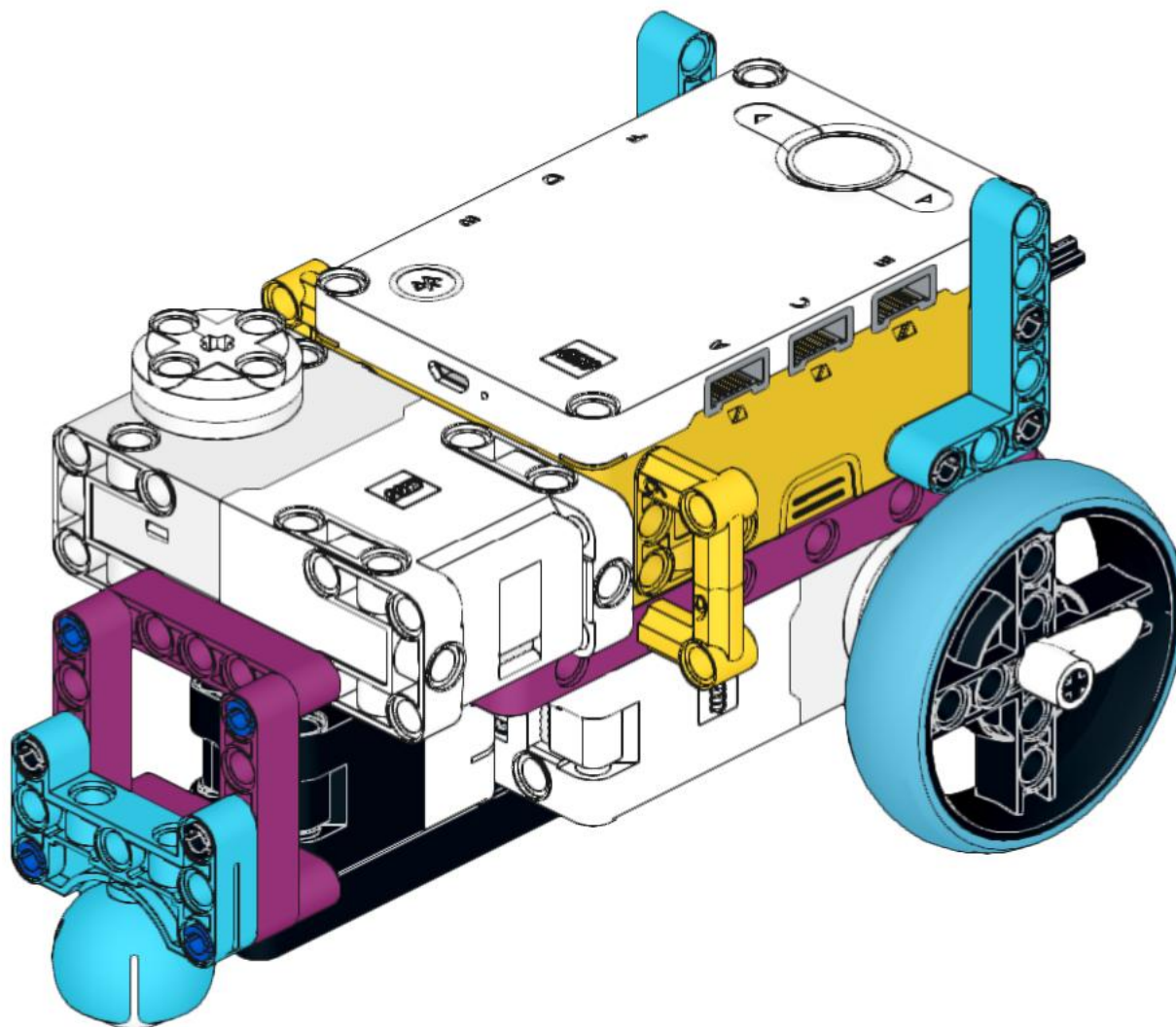
# 23



Use these brackets to help  
organize your wires.

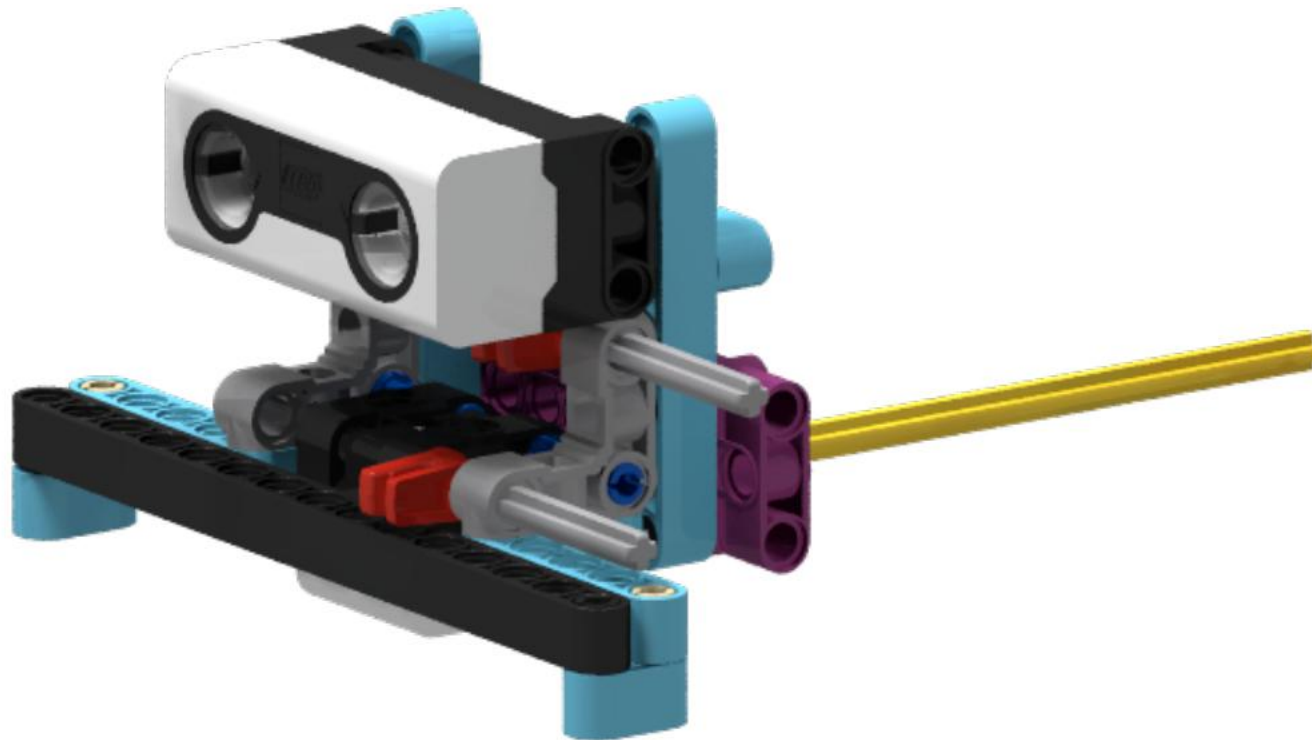


24

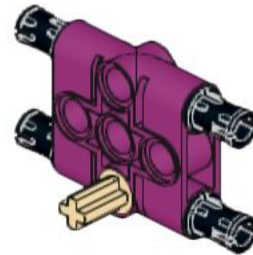
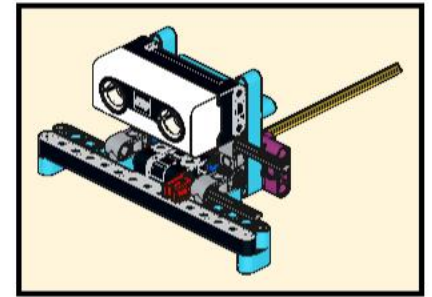
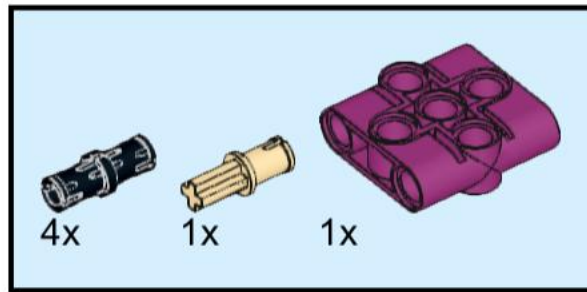




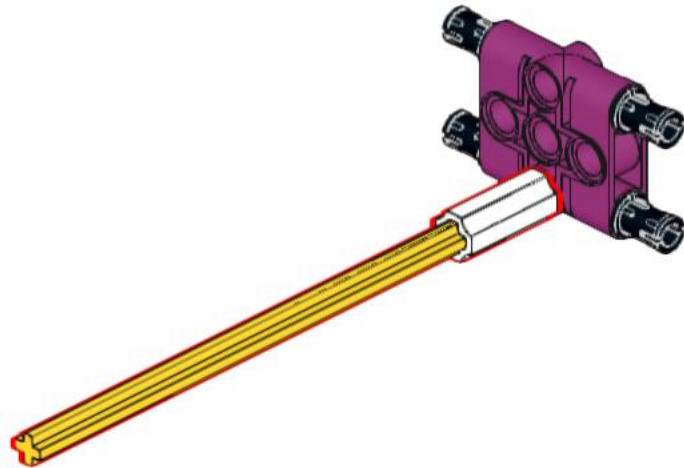
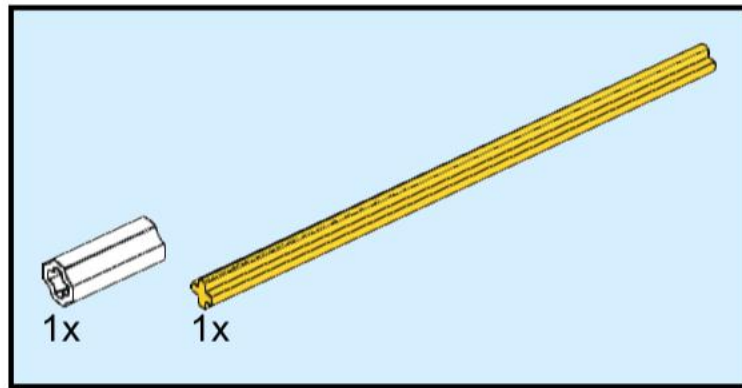
# Sensors



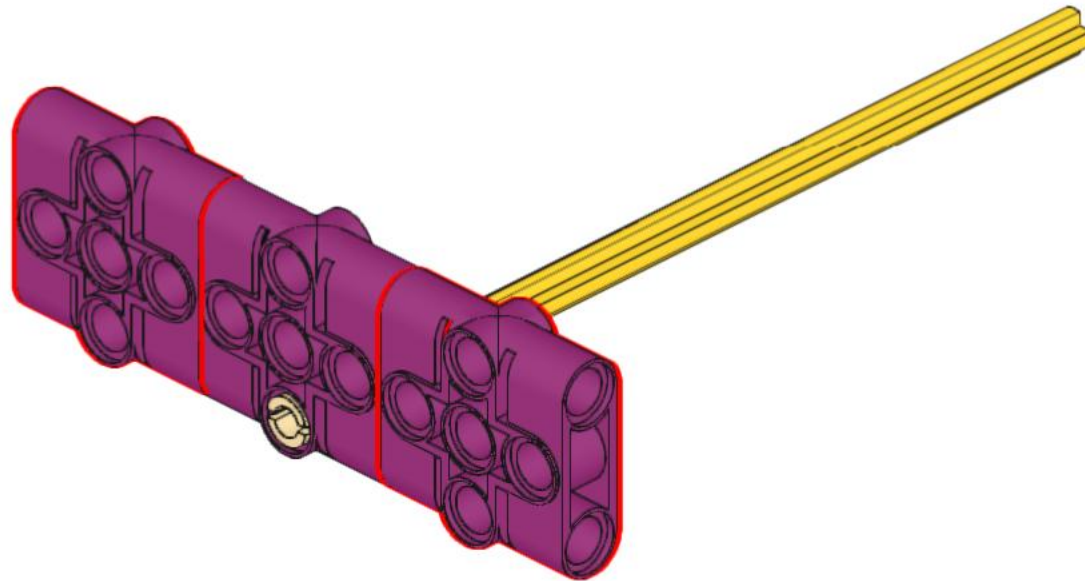
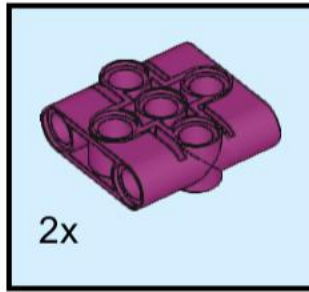
# 25



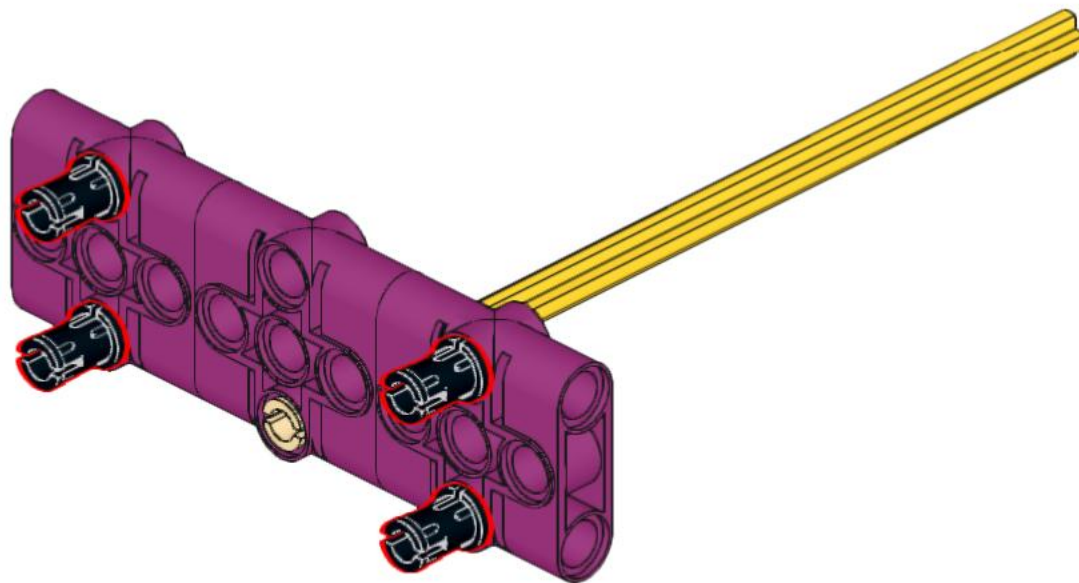
# 26



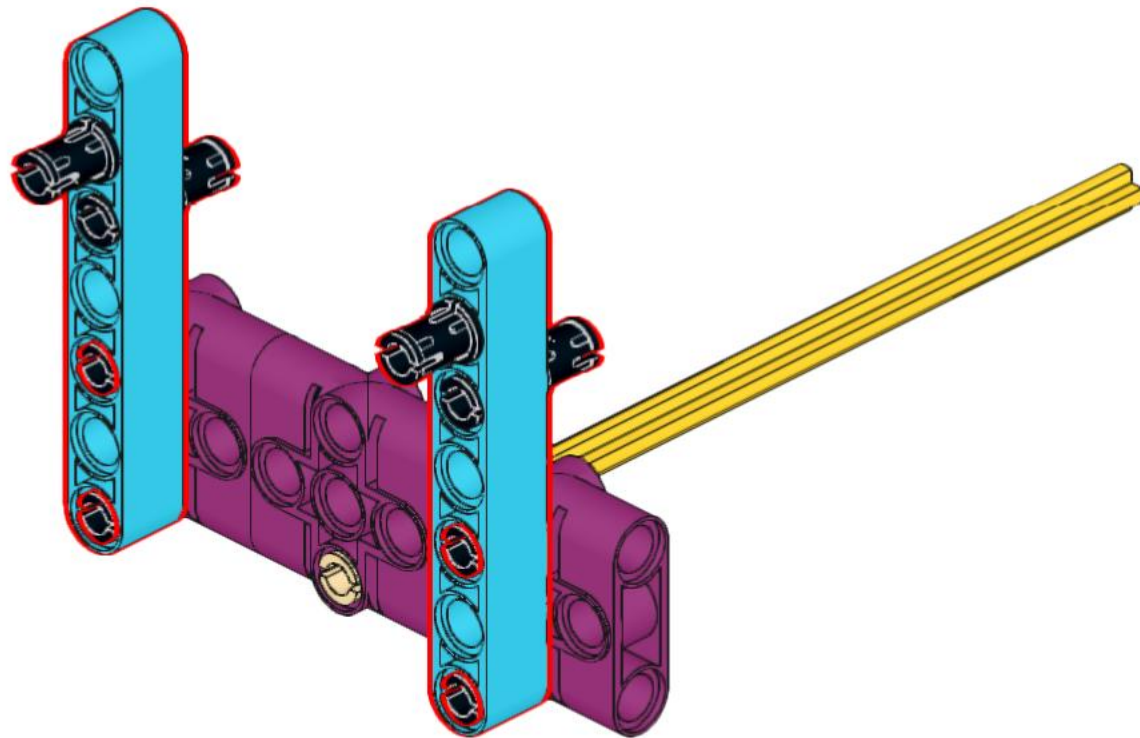
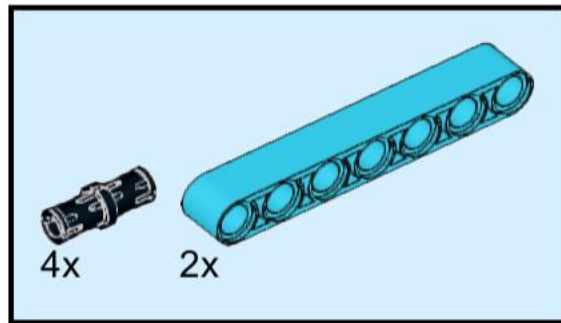
# 27



# 28

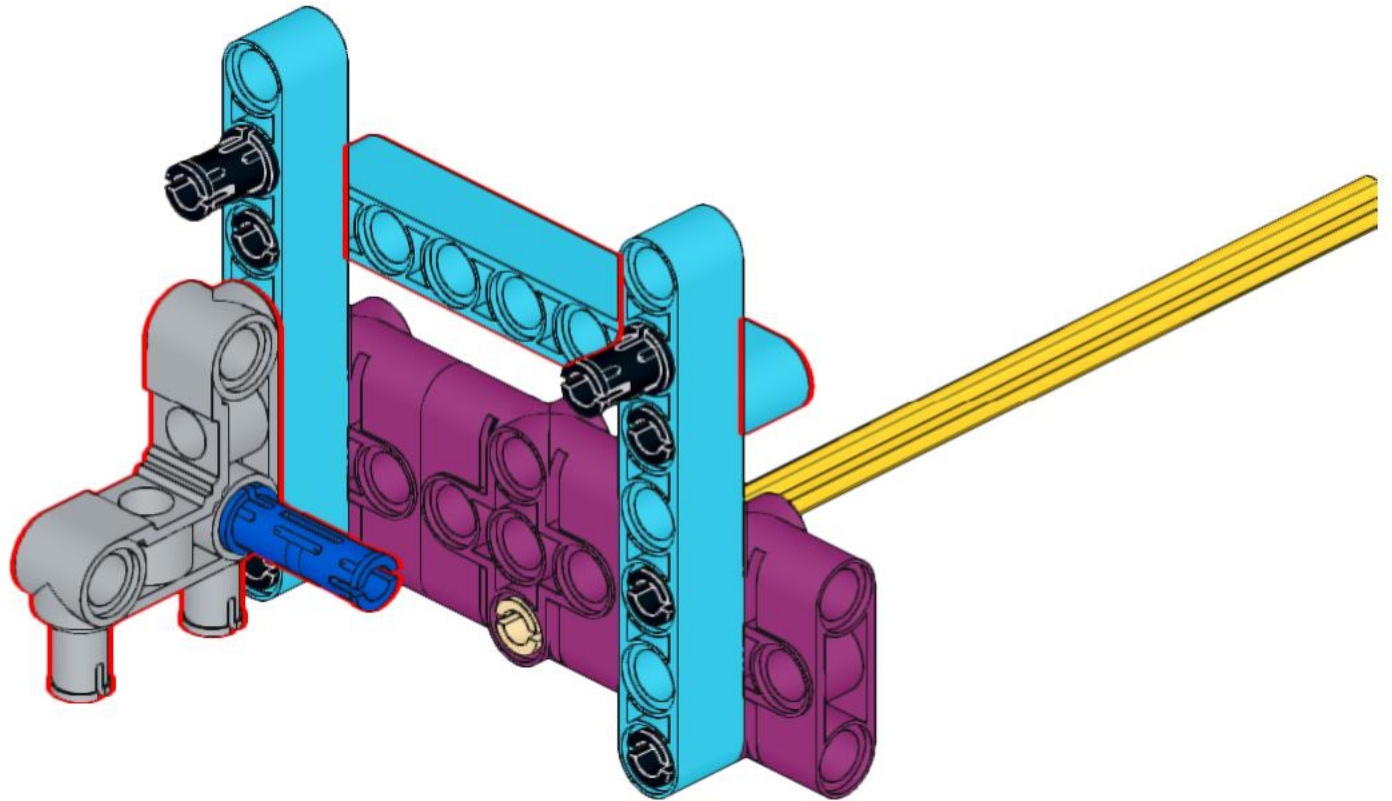
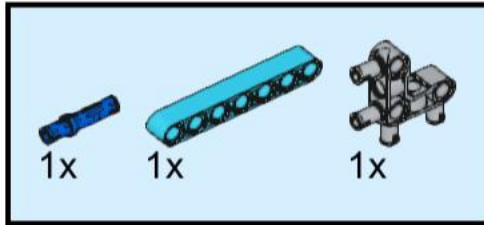


# 29

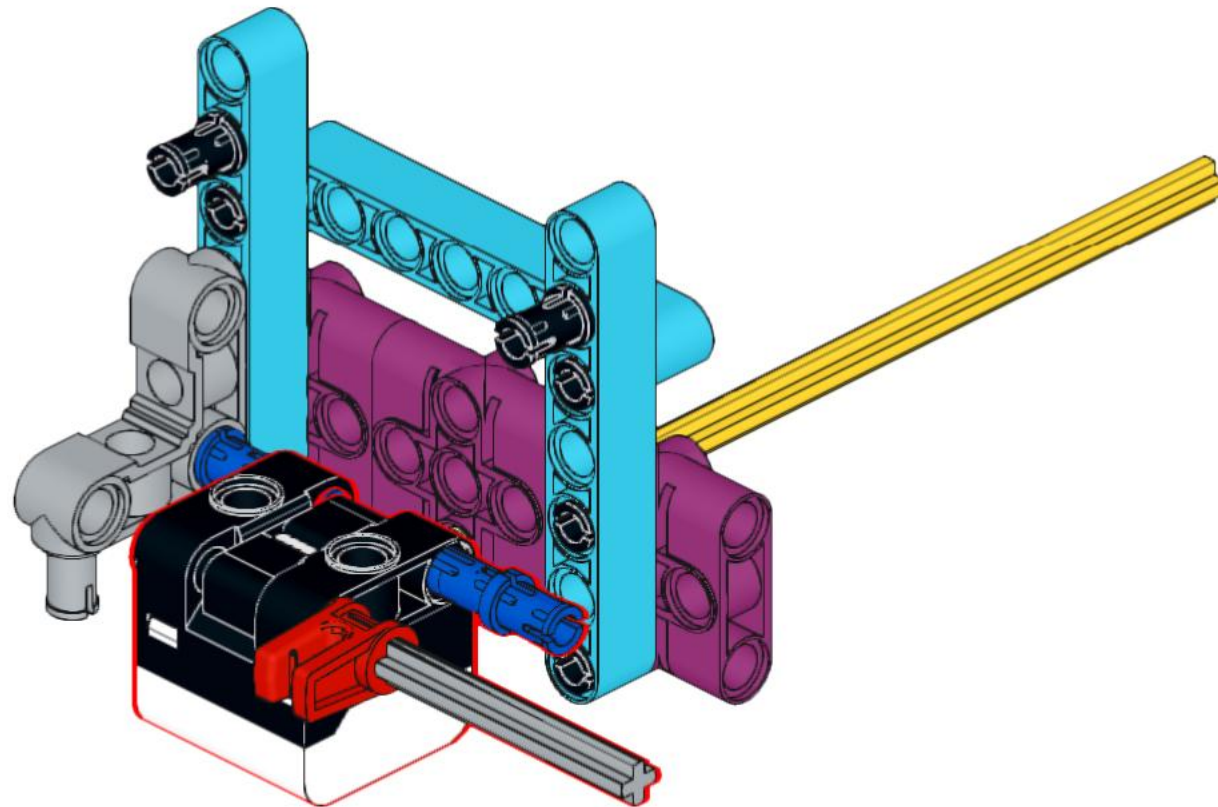
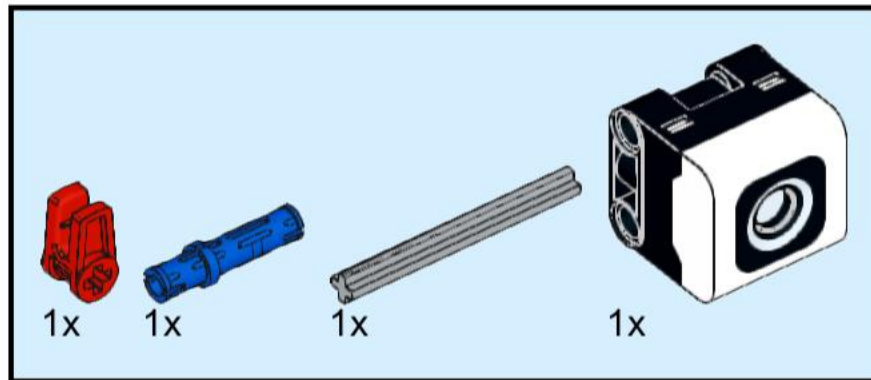




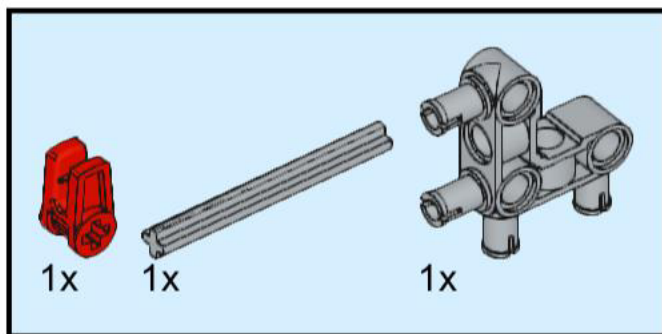
# 30



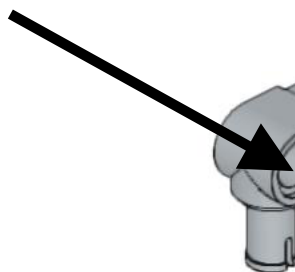
# 31



# 32



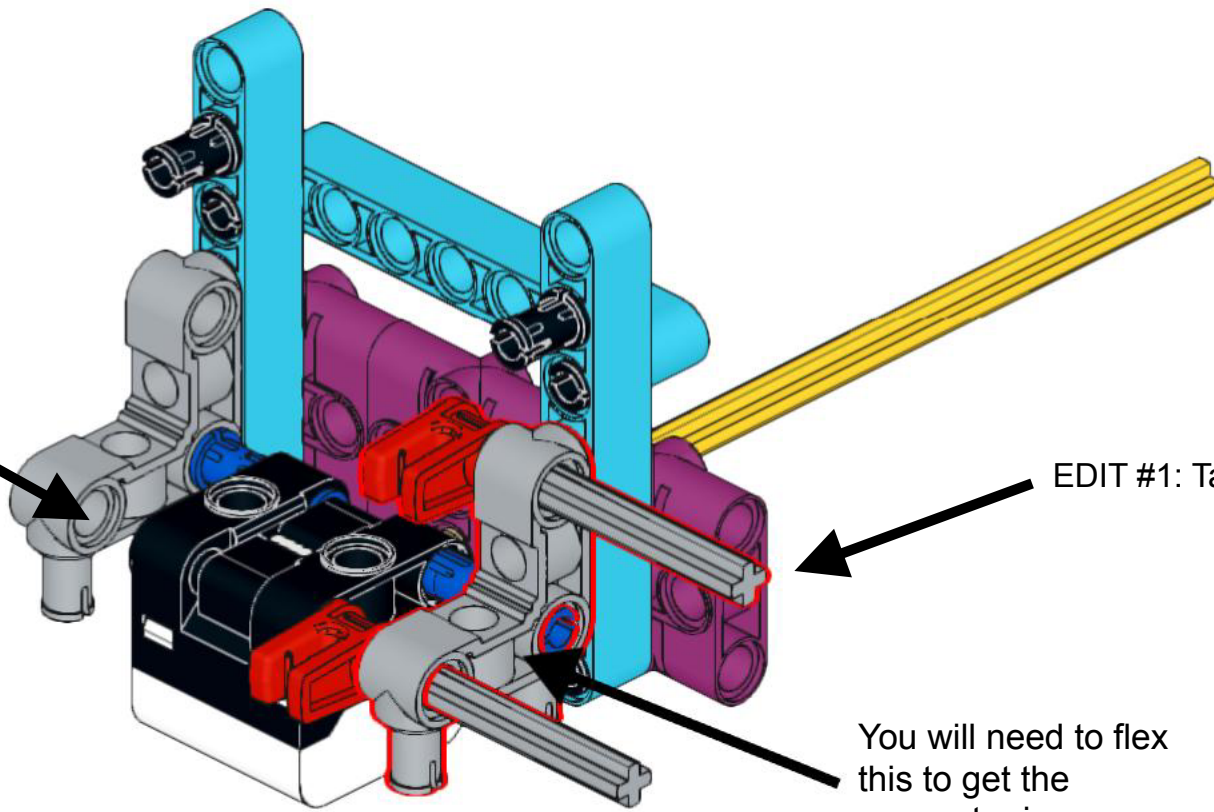
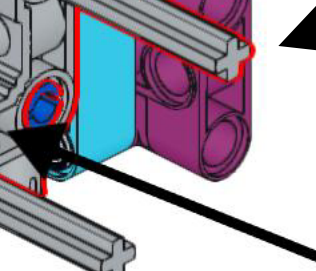
EDIT #2: and put it here



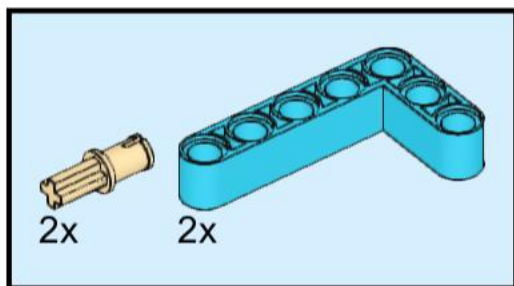
EDIT #1: Take this part



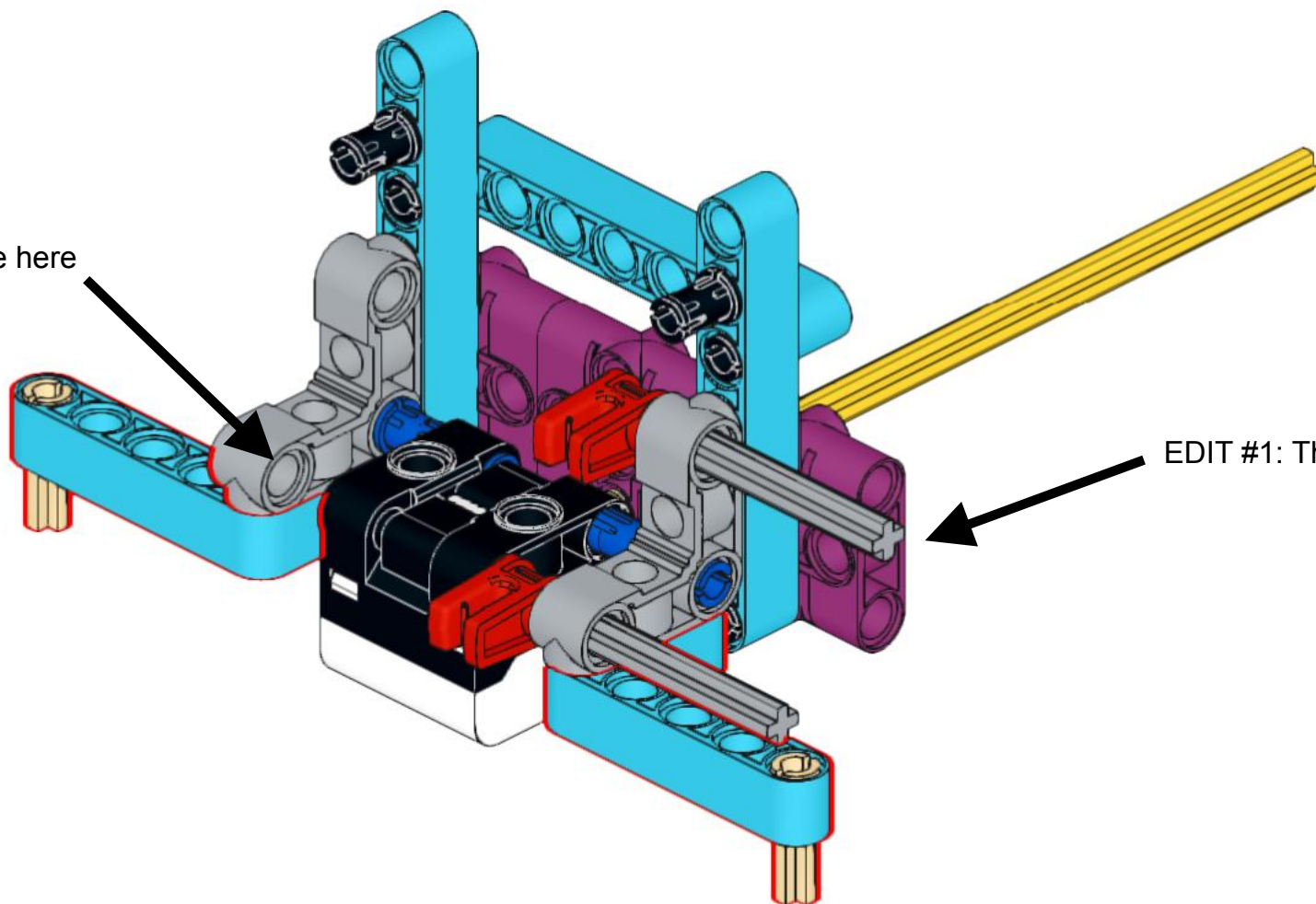
You will need to flex this to get the connector in



# 33

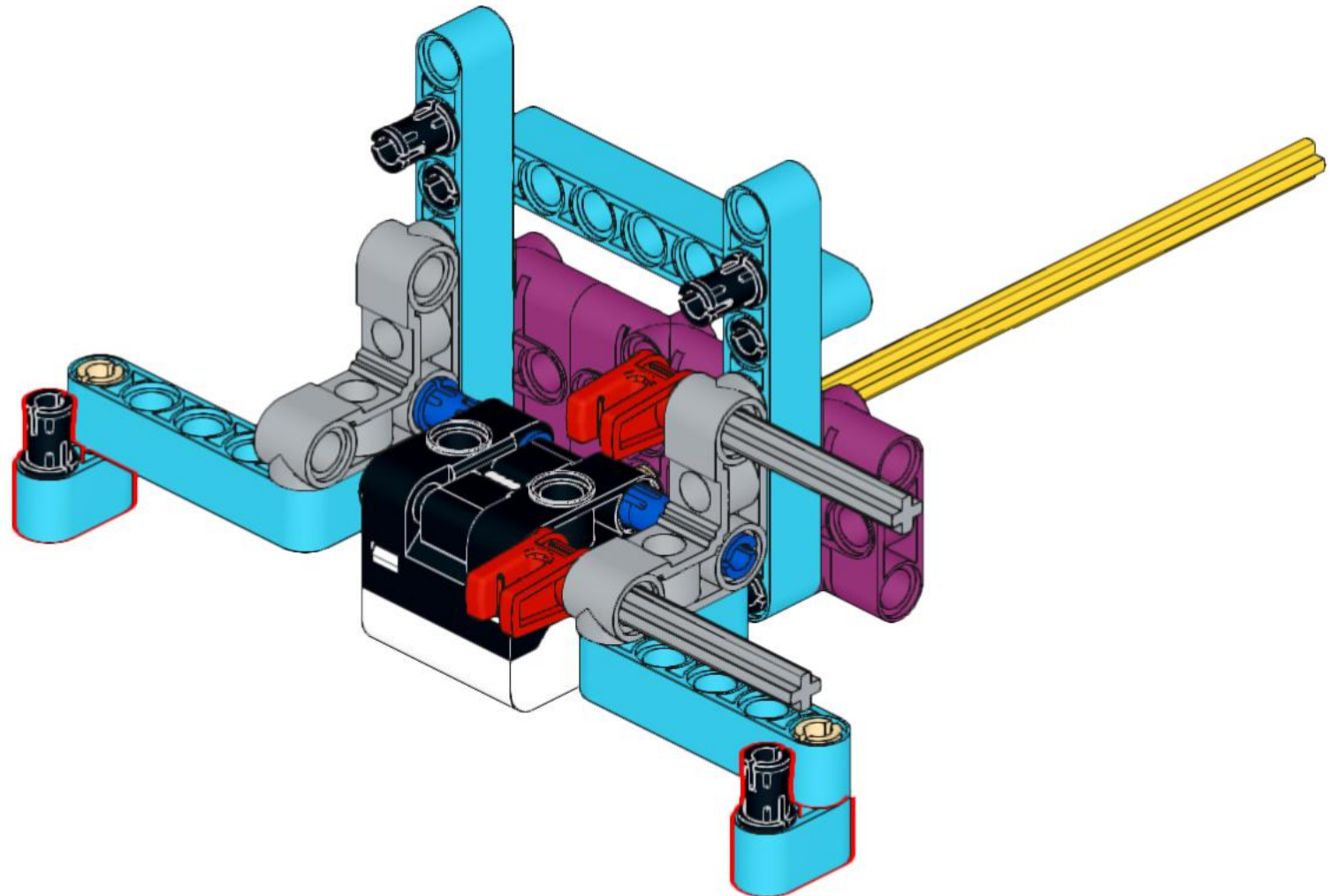
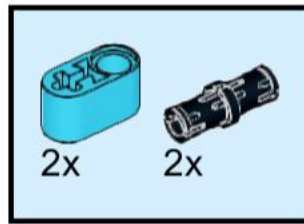


EDIT #2: should be here



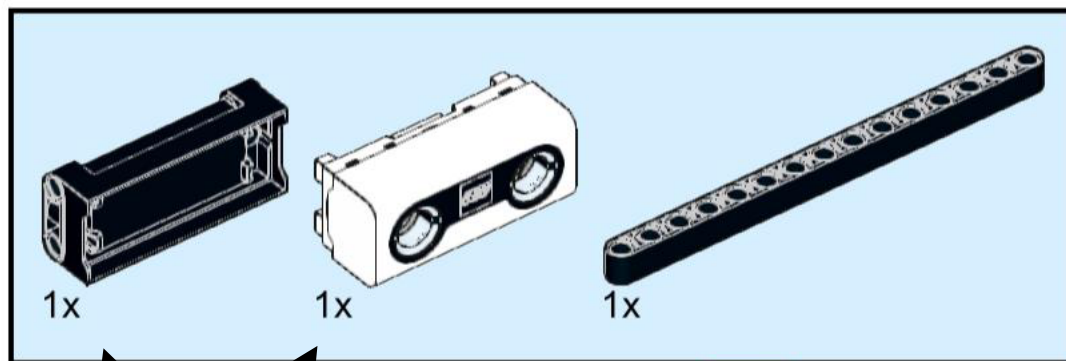
EDIT #1: This part

# 34

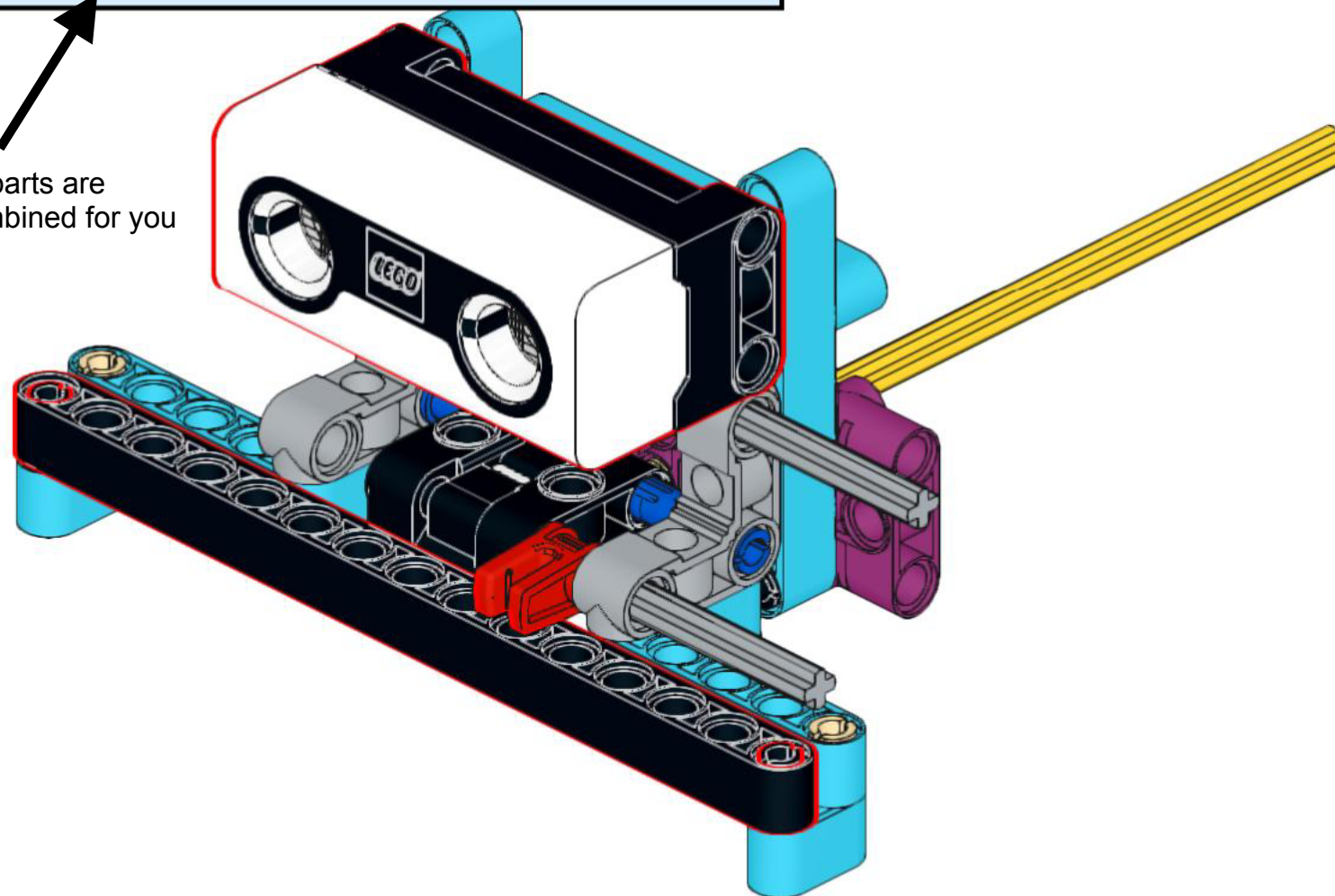




# 35



These two parts are  
already combined for you



# 36

